# SL( $n$ ) covariant vector valuations on polytopes 

Chunna Zeng ${ }^{1,2}$ and Dan Ma ${ }^{3}$<br>${ }^{1}$ School of Mathematical Sciences, Chongqing Normal University, Chongqing 401331, China<br>${ }^{2}$ Institut für Diskrete Mathematik und Geometrie, Technische Universität<br>Wien, Wiedner Hauptstraße 8-10/1046, 1040 Wien, Austria, zengchn@163.com<br>${ }^{3}$ Department of Mathematics, Shanghai Normal University, Shanghai 200234, China, madan@shnu.edu.cn


#### Abstract

All SL $(n)$ covariant vector valuations on convex polytopes in $\mathbb{R}^{n}$ are completely classified without any continuity assumptions. The moment vector turns out to be the only such valuation if $n \geq 3$, while two new functionals show up in dimension two.


## 1 Introduction

The study and classification of geometric notions which are compatible with transformation groups are important tasks in geometry as proposed in Felix Klein's Erlangen program in 1872. As many functions defined on geometric objects satisfy the inclusion-exclusion principle, the property of being a valuation is natural to consider in the classification. Here, a map $\mu: \mathcal{S} \rightarrow\langle\mathcal{A},+\rangle$ is called a valuation on a collection $\mathcal{S}$ of sets with values in an abelian semigroup $\langle\mathcal{A},+\rangle$ if

$$
\mu(P)+\mu(Q)=\mu(P \cup Q)+\mu(P \cap Q)
$$

whenever $P, Q, P \cap Q$ and $P \cup Q$ are contained in $\mathcal{S}$.
2010 Mathematics subject classification. 52B45, 52A20
Key words and phrases. Moment vector, valuation, convex polytope, $\operatorname{SL}(n)$ covariance.

At the beginning of the twentieth century, valuations were first constructed by Dehn in his solution of Hilbert's Third Problem. Nearly 50 years later, Hadwiger initiated a systematic study of valuations by his celebrated characterization theorem. He showed that all continuous and rigid motion invariant valuations on the space of convex bodies (i.e. compact convex sets) in $\mathbb{R}^{n}$ are linear combinations of intrinsic volumes.

The classification of valuations using compatibility with certain linear maps and the topology induced by the Hausdorff metric is a classical part of geometry with important applications in integral geometry (cf. [10], [26, Chap. 6]). Such results turned out to be extremely fruitful and useful especially in the affine geometry of convex bodies. Examples include intrinsic volumes, affine surface areas, the projection body operator and the intersection body operator (cf. [1-6, 8, 9, 11-13, 15-22, 24, 25]).

Recently, Ludwig and Reitzner [23] established a characterization of $\operatorname{SL}(n)$ invariant valuation on $\mathcal{P}^{n}$, the space of convex polytopes in $\mathbb{R}^{n}$, without any continuity assumptions.

Theorem 1.1. A functional $z: \mathcal{P}^{n} \rightarrow \mathbb{R}$ is an $\mathrm{SL}(n)$ invariant valuation if and only if there exist constants $c_{0}, c_{0}^{\prime}, d_{0} \in \mathbb{R}$ and solutions $\alpha, \beta:[0, \infty) \rightarrow \mathbb{R}$ of Cauchy's functional equation such that

$$
z(P)=c_{0} V_{0}(P)+c_{0}^{\prime}(-1)^{\operatorname{dim} P} \chi_{\text {relint } P}(0)+\alpha\left(V_{n}(P)\right)+d_{0} \chi_{P}(0)+\beta\left(V_{n}([0, P])\right)
$$

for every $P \in \mathcal{P}^{n}$, where $V_{0}$ and $V_{n}$ denote the Euler characteristic and the volume, respectively, $[0, P]$ denotes the convex hull of $P$ and the origin and $\chi$ denotes the indicator function.

The aim of this paper is to obtain a complete classification of $\mathrm{SL}(n)$ covariant vector valuations on $\mathcal{P}^{n}$. This also corresponds to the following classification results on $\mathcal{P}_{(0)}^{n}$, the space of convex polytopes containing the origin in their interiors, due to Haberl and Parapatits [7].

Theorem 1.2. Let $n \geq 3$. A functional $\mu: \mathcal{P}_{(0)}^{n} \rightarrow \mathbb{R}^{n}$ is a measurable and $\operatorname{SL}(n)$ covariant valuation if and only if there exists a constant $c \in \mathbb{R}$ such that

$$
\mu(P)=c m(P)
$$

for every $P \in \mathcal{P}_{(0)}^{n}$.
Theorem 1.3. A functional $\mu: \mathcal{P}_{(0)}^{2} \rightarrow \mathbb{R}^{2}$ is a measurable and $\mathrm{SL}(2)$ covariant valuation if and only if there exist constants $c_{1}, c_{2} \in \mathbb{R}$ such that

$$
\mu(P)=c_{1} m(P)+c_{2} \rho_{\frac{\pi}{2}} m\left(P^{*}\right)
$$

for every $P \in \mathcal{P}_{(0)}^{2}$, where $\rho_{\frac{\pi}{2}}$ denotes the counter-clockwise rotation in $\mathbb{R}^{2}$ by the angle $\pi / 2$ and $P^{*}$ denotes the polar body of $P$.

Here, a functional $\mu: \mathcal{P}^{n} \rightarrow \mathbb{R}^{n}$ is called SL $(n)$ covariant if $\mu(\phi P)=\phi \mu(P)$ for all $P \in \mathcal{P}^{n}$ and $\phi \in \operatorname{SL}(n)$. The vector $m(P)$ is the moment vector of $P$, which is defined by

$$
m(P)=\int_{P} x d x
$$

for every $P \in \mathcal{P}^{n}$. It coincides with the centroid of $P$ multiplied by the volume of $P$, which makes it a basic notion in mechanics, engineering, physics and geometry. Earlier results on characterizations of moment vectors can be found in [14, 26]. Throughout this paper, a functional with values in an Euclidean space is called measurable if the preimage of every open set is a Borel set with respect to the corresponding topology.

Denote by $\mathcal{P}_{0}^{n}$ the subspace of convex polytopes containing the origin. First, we consider valuations defined on $\mathcal{P}_{0}^{n}$ and obtain the following result.

Theorem 1.4. Let $n \geq 3$. A functional $\mu: \mathcal{P}_{0}^{n} \rightarrow \mathbb{R}^{n}$ is an $\mathrm{SL}(n)$ covariant valuation if and only if there exists a constant $c \in \mathbb{R}$ such that

$$
\mu(P)=c m(P)
$$

for every $P \in \mathcal{P}_{0}^{n}$.
Solutions of Cauchy's functional equation show up only in dimension two.
Theorem 1.5. A functional $\mu: \mathcal{P}_{0}^{2} \rightarrow \mathbb{R}^{2}$ is an $\mathrm{SL}(2)$ covariant valuation if and only if there exist constants $c_{1}, c_{2} \in \mathbb{R}$ and a solution of Cauchy's functional equation $\alpha:[0, \infty) \rightarrow \mathbb{R}$ such that

$$
\mu(P)=c_{1} m(P)+c_{2} e(P)+h_{\alpha}(P)
$$

for every $P \in \mathcal{P}_{0}^{n}$, where the functionals $e, h_{\alpha}: \mathcal{P}_{0}^{2} \rightarrow \mathbb{R}^{2}$ are defined in Section 2.
Next, we consider the classification of measurable $\mathrm{SL}(2)$ covariant valuations. It is well known that all measurable solutions of Cauchy's functional equation are linear. This immediately leads the following corollary.

Corollary 1.1. A functional $\mu: \mathcal{P}_{0}^{2} \rightarrow \mathbb{R}^{2}$ is a measurable and $\mathrm{SL}(2)$ covariant valuation if and only if there exist constants $c_{1}, c_{2}, c_{3} \in \mathbb{R}$ such that

$$
\mu(P)=c_{1} m(P)+c_{2} e(P)+c_{3} h(P)
$$

for every $P \in \mathcal{P}_{0}^{2}$, where the functional $h: \mathcal{P}_{0}^{2} \rightarrow \mathbb{R}^{2}$ is defined in Section 3.
Next we consider the space of all convex polytopes $\mathcal{P}^{n}$. This step is similar to the classification of convex body valued valuations by Schuster and Wannerer [27] and Wannerer [28].

Theorem 1.6. Let $n \geq 3$. A functional $\mu: \mathcal{P}^{n} \rightarrow \mathbb{R}^{n}$ is an $\mathrm{SL}(n)$ covariant valuation if and only if there exist constants $c_{1}, c_{2} \in \mathbb{R}$ such that

$$
\begin{equation*}
\mu(P)=c_{1} m(P)+c_{2} m([0, P]) \tag{1.1}
\end{equation*}
$$

for every $P \in \mathcal{P}^{n}$.
Again, the case of dimension two is different. We prove the following result.
Theorem 1.7. A functional $\mu: \mathcal{P}^{2} \rightarrow \mathbb{R}^{2}$ is an $\mathrm{SL}(2)$ covariant valuation if and only if there exist constants $c_{1}, c_{2}, \tilde{c}_{1}, \tilde{c}_{2} \in \mathbb{R}$ and solutions of Cauchy's functional equation $\alpha, \gamma:[0, \infty) \rightarrow$ $\mathbb{R}$ such that
$\mu(P)=c_{1} m(P)+\tilde{c}_{1} m([0, P])+c_{2} e(P)+\tilde{c}_{2} e\left(\left[0, v_{1}, \ldots, v_{r}\right]\right)+h_{\alpha}([0, P])+\sum_{i=2}^{r} h_{\gamma}\left(\left[0, v_{i-1}, v_{i}\right]\right)$
for every polytope $P \in \mathcal{P}^{2}$ with vertices $v_{1}, \ldots, v_{r}$ visible from the origin and labeled counterclockwisely, where a vertex $v$ of $P$ is called visible from the origin if $P \cap$ relint $[0, v]=\varnothing$.

Similarly, we have the following corollary.
Corollary 1.2. A functional $\mu: \mathcal{P}^{2} \rightarrow \mathbb{R}^{2}$ is a measurable and $\operatorname{SL}(2)$ covariant valuation if and only if there exist constants $c_{1}, c_{2}, c_{3}, \tilde{c}_{1}, \tilde{c}_{2}, \tilde{c}_{3} \in \mathbb{R}$ such that
$\mu(P)=c_{1} m(P)+\tilde{c}_{1} m([0, P])+c_{2} e([0, P])+c_{3} h([0, P])+\tilde{c}_{2} e\left(\left[0, v_{1}, \ldots, v_{r}\right]\right)+\tilde{c}_{3} h\left(\left[0, v_{1}, \ldots, v_{r}\right]\right)$
for every polytope $P \in \mathcal{P}^{2}$ with vertices $v_{1}, \ldots, v_{r}$ visible from the origin and labeled counterclockwisely.

## 2 Notation and preliminary results

We work in $n$-dimensional Euclidean space $\mathbb{R}^{n}$. The standard basis of $\mathbb{R}^{n}$ consists of $e_{1}, e_{2}, \ldots, e_{n}$. The coordinates of a vector $x \in \mathbb{R}^{n}$ with respect to the standard basis are denoted by $x_{1}, x_{2}, \ldots, x_{n}$. Denote the vector with all coordinates 1 by 1 , the $n \times n$ identity matrix by $I_{n}=\left(e_{1}, \ldots, e_{n}\right)$ and the determinant of a matrix $A$ by $\operatorname{det} A$. The affine hull, the dimension, the interior, the relative interior and the boundary of a given set in $\mathbb{R}^{n}$ are denoted by dim, aff, int, relint and bd, respectively.

The convex hull of $k+1$ affinely independent points is called a $k$-dimensional simplex for all natural number $k$. Generally, we denote by $\left[v_{1}, v_{2}, \ldots, v_{k}\right]$ the convex hull of $v_{1}, v_{2}, \ldots, v_{k} \in$ $\mathbb{R}^{n}$. Two special simplices are the $k$-dimensional standard simplex $T^{k}=\left[0, e_{1}, e_{2}, \ldots, e_{k}\right]$ and
$\tilde{T}^{k-1}=\left[e_{1}, e_{2}, \ldots, e_{k}\right]$, which is a $(k-1)$-dimensional simplex. For $i=1, \ldots, n$, let $\mathcal{T}^{i}$ be the set of $i$-dimensional simplices with one vertex at the origin and $\tilde{\mathcal{T}}^{i-1}$ be the set of ( $i-1$ )-dimensional simplices $T \subset \mathbb{R}^{n}$ with $0 \notin$ aff $T$.

We now recall some basic results on valuations (cf. [10,24]). Let $\mathcal{Q}^{n}$ be either $\mathcal{P}^{n}$ or $\mathcal{P}_{0}^{n}$. The first lemma is the inclusion-exclusion principle.

Lemma 2.1. Let $\mathcal{A}$ be an abelian group and $\mu: \mathcal{Q}^{n} \rightarrow \mathcal{A}$ be a valuation. Then

$$
\mu\left(P_{1} \cup \cdots \cup P_{k}\right)=\sum_{\varnothing \neq S \subseteq\{1,2, \ldots, k\}}(-1)^{|S|-1} \mu\left(\bigcap_{i \in S} P_{i}\right)
$$

for all $k \in \mathbb{N}$ and $P_{1}, P_{2}, \ldots, P_{k} \in \mathcal{Q}^{n}$ with $P_{1} \cup \cdots \cup P_{k} \in \mathcal{Q}^{n}$.
We define a triangulation of a $k$-dimensional polytope $P$ into simplices as a set of $k$ dimensional simplices $\left\{T_{1}, \ldots, T_{r}\right\}$ which have pairwise disjoint interiors, with $P=\cup T_{i}$ and with the property that for arbitrary $1 \leq i_{1}<\cdots<i_{j} \leq r$ the intersections $T_{i_{1}} \cap \cdots \cap T_{i_{j}}$ are again simplices. Therefore we can make full use of the inclusion-exclusion principle (cf. [24]).

Lemma 2.2. Let $\mathcal{A}$ be an abelian group and $\mu: \mathcal{P}_{0}^{n} \rightarrow \mathcal{A}$ be a valuation. Then $\mu$ is determined by its values on $n$-dimensional simplices with one vertex at the origin and its value on $\{0\}$.

A valuation on $\mathcal{Q}^{n}$ is called simple if $\mu(P)=0$ for all $P \in \mathcal{Q}^{n}$ with $\operatorname{dim} P<n$.
Denote by $\mathrm{SL}^{ \pm}(n)$ the group of volume-preserving linear maps, i.e., those with determinant 1 or -1 . A functional $\mu: \mathcal{Q}^{n} \rightarrow \mathbb{R}^{n}$ is called $\mathrm{SL}^{ \pm}(n)$ covariant if $\mu(\phi P)=\phi \mu(P)$ for all $P \in \mathcal{Q}^{n}$ and $\phi \in \mathrm{SL}^{ \pm}(n)$ and, following [7], it is called $\mathrm{SL}^{ \pm}(n)$ signum covariant if $\mu(\phi P)=(\operatorname{det} \phi) \phi \mu(P)$ for all $P \in \mathcal{Q}^{n}$ and $\phi \in \mathrm{SL}^{ \pm}(n)$. Let $\mu: \mathcal{Q}^{n} \rightarrow \mathbb{R}^{n}$ be an $\operatorname{SL}(n)$ covariant valuation. We have $\mu=\mu^{+}+\mu^{-}$, where

$$
\mu^{+}(P)=\frac{1}{2}\left(\mu(P)+\theta \mu\left(\theta^{-1} P\right)\right) \quad \text { and } \quad \mu^{-}(P)=\frac{1}{2}\left(\mu(P)-\theta \mu\left(\theta^{-1} P\right)\right)
$$

for some fixed $\theta \in \mathrm{SL}^{ \pm}(n) \backslash \mathrm{SL}(n)$. Clearly, $\mu^{+}$and $\mu^{-}$are valuations. Moreover, it is not hard to see that $\mu^{+}$is $\mathrm{SL}^{ \pm}(n)$ covariant and $\mu^{-}$is $\mathrm{SL}^{ \pm}(n)$ signum covariant.

The solution of Cauchy's functional equation is one of the main ingredients in our proof. Since we do not assume continuity, functionals also depend on solutions $\alpha:[0, \infty) \rightarrow \mathbb{R}$ of Cauchy's functional equation, that is,

$$
\alpha(s+t)=\alpha(s)+\alpha(t)
$$

for all $s, t \in[0, \infty)$. If we add the condition that $\alpha$ is measurable, then $\alpha$ has to be linear.
Let $\lambda \in(0,1)$ and denote by $H$ the hyperplane through the origin with the normal vector $(1-\lambda) e_{1}-\lambda e_{2}$. Write $H^{+}$and $H^{-}$as the two halfspaces bounded by $H$. This hyperplane
induces a series of dissections of $T^{i}$ as well as $\tilde{T}^{i-1}$ for $i=2, \ldots, n$. Let $\mu: \mathcal{Q}^{n} \rightarrow \mathbb{R}^{n}$ be an $\mathrm{SL}(n)$ covariant valuation. There are two interpolations corresponding to these dissections. First, assume that $i<n$. By the inclusion-exclusion principle, we get

$$
\begin{equation*}
\mu\left(T^{i}\right)+\mu\left(T^{i} \cap H\right)=\mu\left(T^{i} \cap H^{+}\right)+\mu\left(T^{i} \cap H^{-}\right) \tag{2.1}
\end{equation*}
$$

Definition 1. Let $\lambda \in(0,1)$. The linear transform $\phi_{1} \in \mathrm{SL}(n)$ is given by

$$
\phi_{1} e_{1}=\lambda e_{1}+(1-\lambda) e_{2}, \phi_{1} e_{2}=e_{2}, \phi_{1} e_{n}=e_{n} / \lambda, \phi_{1} e_{j}=e_{j} \text { for } 3 \leq j \leq n-1,
$$

and $\psi_{1} \in \mathrm{SL}(n)$ is given by

$$
\psi_{1} e_{1}=e_{1}, \psi_{1} e_{2}=\lambda e_{1}+(1-\lambda) e_{2}, \psi_{1} e_{n}=e_{n} /(1-\lambda), \psi_{1} e_{j}=e_{j} \text { for } 3 \leq j \leq n-1
$$

It is clear that $T^{i} \cap H^{+}=\psi_{1} T^{i}, T^{i} \cap H^{-}=\phi_{1} T^{i}$ and $T^{i} \cap H=\phi_{1} T^{i-1}$. Then, equation (2.1) becomes

$$
\mu\left(T^{i}\right)+\mu\left(\phi_{1} T^{i-1}\right)=\mu\left(\phi_{1} T^{i}\right)+\mu\left(\psi_{1} T^{i}\right) .
$$

Since $\mu$ is $\operatorname{SL}(n)$ covariance, we derive

$$
\begin{equation*}
\left(\phi_{1}+\psi_{1}-I_{n}\right) \mu\left(T^{i}\right)=\phi_{1} \mu\left(T^{i-1}\right) \tag{2.2}
\end{equation*}
$$

Second, we consider the dissection of $s T^{n}$ for $s>0$. Again, by the inclusion-exclusion principle, we have

$$
\begin{equation*}
\mu\left(s T^{n}\right)+\mu\left(s T^{n} \cap H\right)=\mu\left(s T^{n} \cap H^{+}\right)+\mu\left(s T^{n} \cap H^{-}\right) \tag{2.3}
\end{equation*}
$$

Definition 2. Let $\lambda \in(0,1)$. The linear transform $\phi_{2} \in \mathrm{GL}(n)$ is given by

$$
\phi_{2} e_{1}=\lambda e_{1}+(1-\lambda) e_{2}, \phi_{2} e_{2}=e_{2}, \phi_{2} e_{j}=e_{j} \text { for } 3 \leq j \leq n,
$$

and $\psi_{2} \in \mathrm{GL}(n)$ is given by

$$
\psi_{2} e_{1}=e_{1}, \psi_{2} e_{2}=\lambda e_{1}+(1-\lambda) e_{2}, \psi_{2} e_{j}=e_{j} \text { for } 3 \leq j \leq n
$$

It is clear that $s T^{n} \cap H^{+}=\psi_{2} s T^{n}, s T^{n} \cap H^{-}=\phi_{2} s T^{n}$ and $s T^{n} \cap H=\phi_{2} s T^{n-1}$. Then, equation (2.3) becomes

$$
\mu\left(s T^{n}\right)+\mu\left(\phi_{2} s T^{n-1}\right)=\mu\left(\phi_{2} s T^{n}\right)+\mu\left(\psi_{2} s T^{n}\right)
$$

Since $\phi_{2} / \sqrt[n]{\lambda}$ and $\psi_{2} / \sqrt[n]{1-\lambda}$ belong to $\operatorname{SL}(n)$, we obtain

$$
\mu\left(s T^{n}\right)+\lambda^{-1 / n} \phi_{2} \mu\left(\sqrt[n]{\lambda} s T^{n-1}\right)=\lambda^{-1 / n} \phi_{2} \mu\left(\sqrt[n]{\lambda} s T^{n}\right)+(1-\lambda)^{-1 / n} \psi_{2} \mu\left(\sqrt[n]{1-\lambda} s T^{n}\right) .
$$

Replacing $s$ by $\sqrt[n]{s}$ in the equation above yields

$$
\begin{equation*}
\mu\left(\sqrt[n]{s} T^{n}\right)+\lambda^{-1 / n} \phi_{2} \mu\left(\sqrt[n]{\lambda s} T^{n-1}\right)=\lambda^{-1 / n} \phi_{2} \mu\left(\sqrt[n]{\lambda s} T^{n}\right)+(1-\lambda)^{-1 / n} \psi_{2} \mu\left(\sqrt[n]{(1-\lambda) s} T^{n}\right) \tag{2.4}
\end{equation*}
$$

On $\mathcal{P}_{0}^{2}$, two new functionals appear in the classification results. Define $e: \mathcal{P}_{0}^{2} \rightarrow \mathbb{R}^{2}$ by

$$
e(P)=v+w
$$

if $\operatorname{dim} P=2$ and $P$ has two edges $[0, v]$ and $[0, w]$, or $\operatorname{dim} P=2$ and $P$ has an edge $[v, w]$ that contains the origin in its relative interior;

$$
e(P)=2(v+w)
$$

if $\operatorname{dim} P=1$ and $P=[v, w]$ contains the origin;

$$
e(P)=0
$$

otherwise.
In order to prove that $e$ is a valuation on $\mathcal{P}_{0}^{2}$, we use the following terminology. We say $\mu$ defined on $\mathcal{P}_{0}^{2}$ is a weak valuation, if

$$
\begin{equation*}
\mu\left(P \cap L^{+}\right)+\mu\left(P \cap L^{-}\right)=\mu(P)+\mu(P \cap L) \tag{2.5}
\end{equation*}
$$

for every $P \in \mathcal{P}_{0}^{2}$ and line $L$ through the origin in the plane, where $L^{+}$and $L^{-}$are two half planes bounded by $L$. Indeed, we have the following implication. (see [26, Theorem 6.2.3] for a version on $\mathcal{P}^{2}$ )

Lemma 2.3. Every weak valuation is a valuation on $\mathcal{P}_{0}^{2}$.
Proof. Let $\mu$ be a weak valuation on $\mathcal{P}_{0}^{2}$. Write $S_{0}^{2}$ as the space of triangles in $\mathbb{R}^{2}$ with one vertex at the origin. Note that $S_{0}^{2}$ is a generating set of $\mathcal{P}_{0}^{2}$, i.e. a subset of $\mathcal{P}_{0}^{2}$ that is closed under finite intersections and such that every element of $\mathcal{P}_{0}^{2}$ is a finite union of elements therein. Due to Groemer's integral theorem (cf. [10, Theorem 2.2.1]), it suffices to show that $\mu$ is a valuation on $S_{0}^{2}$.

Let $S_{1}, S_{2} \in S_{0}^{2}$ with $S=S_{1} \cup S_{2} \in S_{0}^{2}$ as well. The statement is trivial if one of them includes the other. Otherwise, write $S_{3}=S_{1} \cap S_{2}$. There are two cases.

First, if $S_{3}$ is line segment, write $L=\operatorname{span} S_{3}$. Without loss of generality, assume $S_{1}=$ $S \cap L^{+}$and $S_{2}=S \cap L^{-}$. Since $\mu$ is a weak valuation, we have

$$
\begin{aligned}
\mu\left(S_{1}\right)+\mu\left(S_{2}\right) & =\mu\left(S \cap L^{+}\right)+\mu\left(S \cap L^{-}\right) \\
& =\mu(S)+\mu(S \cap L)=\mu\left(S_{1} \cup S_{2}\right)+\mu\left(S_{1} \cap S_{2}\right)
\end{aligned}
$$

Next, if $\operatorname{dim} S_{3}=2$, write $S_{4}=\operatorname{cl}\left(S_{1} \backslash S_{3}\right), S_{5}=\operatorname{cl}\left(S_{2} \backslash S_{3}\right), L_{1}=\operatorname{span}\left(S_{3} \cap S_{4}\right)$ and $L_{2}=\operatorname{span}\left(S_{3} \cap S_{5}\right)$. Without loss of generality, assume $S_{4}=S_{1} \cap L_{1}^{+}, S_{3}=S_{1} \cap L_{1}^{-}=S_{2} \cap L_{2}^{+}$ and $S_{5}=S_{2} \cap L_{2}^{-}$. Since $\mu$ is a weak valuation, we have

$$
\mu\left(S_{3}\right)+\mu\left(S_{4}\right)=\mu\left(S_{1} \cap L_{1}^{-}\right)+\mu\left(S_{1} \cap L_{1}^{+}\right)=\mu\left(S_{1}\right)+\mu\left(S_{3} \cap S_{4}\right)
$$

and

$$
\mu\left(S_{3}\right)+\mu\left(S_{5}\right)=\mu\left(S_{2} \cap L_{2}^{+}\right)+\mu\left(S_{2} \cap L_{2}^{-}\right)=\mu\left(S_{2}\right)+\mu\left(S_{3} \cap S_{5}\right)
$$

Summing the two equations above gives

$$
\mu\left(S_{1} \cup S_{2}\right)+\mu\left(S_{1} \cap S_{2}\right)=\mu(S)+\mu\left(S_{3}\right)=\mu\left(S_{1}\right)+\mu\left(S_{2}\right)
$$

Therefore, $\mu$ is a valuation on $\mathcal{P}_{0}^{2}$.
Lemma 2.4. The functional e is an $\mathrm{SL}(2)$ covariant valuation on $\mathcal{P}_{0}^{2}$.
Proof. By the definition, it is clear that $e$ is $\mathrm{SL}(2)$ covariant.
Next, we are going to prove that $e$ is a valuation on $\mathcal{P}_{0}^{2}$. Due to Lemma 2.3, it suffices to show that $e$ is a weak valuation via the following four cases.

First, let $\operatorname{dim} P=2$ and $P$ has two edges $[0, v]$ and $[0, w]$. Then, we have $e(P)=v+w$. Assume that a line $L$ through the origin intersects an edge of $P$ at $u$. It follows that $e\left(P \cap L^{+}\right)=w+u, e\left(P \cap L^{-}\right)=u+v$ and $e(P \cap L)=2 u$.

Second, let $\operatorname{dim} P=2$ and $P$ has an edge $[v, w]$ that contains the origin in its relative interior. Then, we have $e(P)=v+w$. Assume that a line $L$ through the origin intersects an edge of $P$ at $u$. It follows that $e\left(P \cap L^{+}\right)=w+u, e\left(P \cap L^{-}\right)=u+v$ and $e(P \cap L)=2 u$.

Third, let $\operatorname{dim} P=2$ and $P$ contains the origin in its interior. Then, we have $e(P)=0$. Assume that a line $L$ through the origin intersects two edges of $P$ at $v$ and $w$ respectively,. It follows that $e\left(P \cap L^{+}\right)=v+w, e\left(P \cap L^{-}\right)=v+w$ and $e(P \cap L)=2(v+w)$.

Finally, let $\operatorname{dim} P=1$ and $P=[v, w]$ contains the origin. Then, we have $e(P)=2(v+w)$. For every line $L$ through the origin, we get $e\left(P \cap L^{+}\right)=2 w, e\left(P \cap L^{-}\right)=2 v$ and $e(P \cap L)=$ 0 .

Let $\alpha:[0, \infty) \rightarrow \mathbb{R}$ be a solution of Cauchy's functional equation. Define $h_{\alpha}: \mathcal{P}_{0}^{2} \rightarrow \mathbb{R}^{2}$ by

$$
h_{\alpha}(P)=\sum_{i=2}^{r} \frac{\alpha\left(\operatorname{det}\left(v_{i-1}, v_{i}\right)\right)}{\operatorname{det}\left(v_{i-1}, v_{i}\right)}\left(v_{i-1}-v_{i}\right)
$$

if $\operatorname{dim} P=2$ and $P=\left[0, v_{1}, \ldots, v_{r}\right]$ with $0 \in \operatorname{bd} P$ and the vertices $\left\{0, v_{1}, \ldots, v_{r}\right\}$ are labeled counter-clockwisely;

$$
h_{\alpha}(P)=\frac{\alpha\left(\operatorname{det}\left(v_{r}, v_{1}\right)\right)}{\operatorname{det}\left(v_{r}, v_{1}\right)}\left(v_{r}-v_{1}\right)+\sum_{i=2}^{r} \frac{\alpha\left(\operatorname{det}\left(v_{i-1}, v_{i}\right)\right)}{\operatorname{det}\left(v_{i-1}, v_{i}\right)}\left(v_{i-1}-v_{i}\right)
$$

if $0 \in \operatorname{int} P$ and $P=\left[v_{1}, \ldots, v_{r}\right]$ with the vertices $\left\{v_{1}, \ldots, v_{r}\right\}$ are labeled counter-clockwisely;

$$
h_{\alpha}(P)=0
$$

if $P=\{0\}$ or $P$ is a line segment.
Lemma 2.5. If $\alpha:[0, \infty) \rightarrow \mathbb{R}$ is a solution of Cauchy's functional equation, then the functional $h_{\alpha}$ is an $\mathrm{SL}(2)$ covariant valuation on $\mathcal{P}_{0}^{2}$.
Proof. Let $\alpha:[0, \infty) \rightarrow \mathbb{R}$ be a solution of Cauchy's functional equation. We write $\alpha^{*}=$ $\alpha(s) / s$ for $s>0$. As a first step, we show that $h_{\alpha}$ is $\mathrm{SL}(2)$ covariant. First, let $P \in \mathcal{P}_{0}^{2}$ and $\operatorname{dim} P=2$. If $P=\left[0, v_{1}, \ldots, v_{r}\right]$ or $P=\left[v_{1}, \ldots, v_{r}\right]$ with $0 \in\left[v_{1}, v_{r}\right]$, then

$$
\begin{aligned}
h_{\alpha}(\phi P) & =\sum_{i=2}^{r} \alpha^{*}\left(\operatorname{det}\left(\phi v_{i-1}, \phi v_{i}\right)\right)\left(\phi v_{i-1}-\phi v_{i}\right) \\
& =\phi \sum_{i=2}^{r} \alpha^{*}\left(\operatorname{det}\left(v_{i-1}, v_{i}\right)\right)\left(v_{i-1}-v_{i}\right) \\
& =\phi h_{\alpha}(P)
\end{aligned}
$$

for every $\phi \in \mathrm{SL}(2)$. Similarly, if $0 \in \operatorname{int} P$, we also have $h_{\alpha}(\phi P)=\phi h_{\alpha}(P)$ for every $\phi \in \operatorname{SL}(2)$. If $P=\{0\}$ or $\operatorname{dim} P=1$, then $h_{\alpha}(\phi P)=\phi h_{\alpha}(P)=0$ for every $\phi \in \operatorname{SL}(2)$.

As a second step, we are going to show that $h_{\alpha}$ is a valuation on $\mathcal{P}_{0}^{2}$. Due to Lemma 2.3, it suffices to show that $h_{\alpha}$ is a weak valuation via the following two cases.

First, let $\operatorname{dim} P=2$ and $P=\left[0, v_{1}, \ldots, v_{r}\right]$ with $0 \in \operatorname{bd} P$ and the vertices $\left\{0, v_{1}, \ldots, v_{r}\right\}$ labeled counter-clockwisely. Then, we have

$$
h_{\alpha}(P)=\sum_{i=2}^{r} \alpha^{*}\left(\operatorname{det}\left(v_{i-1}, v_{i}\right)\right)\left(v_{i-1}-v_{i}\right) .
$$

(i) Assume $L$ passes through a vertex of $P$, say $v_{j}$. Without loss of generality, we have $P \cap L^{+}=\left[0, v_{1}, \ldots, v_{j}\right]$ and $P \cap L^{-}=\left[0, v_{j}, \ldots, v_{r}\right]$. Thus,
$h_{\alpha}\left(P \cap L^{+}\right)=\sum_{i=2}^{j} \alpha^{*}\left(\operatorname{det}\left(v_{i-1}, v_{i}\right)\right)\left(v_{i-1}-v_{i}\right)$ and $h_{\alpha}\left(P \cap L^{-}\right)=\sum_{i=j+1}^{r} \alpha^{*}\left(\operatorname{det}\left(v_{i-1}, v_{i}\right)\right)\left(v_{i-1}-v_{i}\right)$.
(ii) Assume $L$ intersects the edge $\left[v_{j}, v_{j+1}\right]$ at $u$. Without loss of generality, we have $P \cap L^{+}=\left[0, v_{1}, \ldots, v_{j}, u\right]$ and $P \cap L^{-}=\left[0, u, v_{j+1}, \ldots, v_{r}\right]$. Thus,

$$
h_{\alpha}\left(P \cap L^{+}\right)=\alpha^{*}\left(\operatorname{det}\left(v_{j}, u\right)\right)\left(v_{j}-u\right)+\sum_{i=2}^{j} \alpha^{*}\left(\operatorname{det}\left(v_{i-1}, v_{i}\right)\right)\left(v_{i-1}-v_{i}\right)
$$

and

$$
h_{\alpha}\left(P \cap L^{-}\right)=\alpha^{*}\left(\operatorname{det}\left(u, v_{j+1}\right)\right)\left(u-v_{j+1}\right)+\sum_{i=j+2}^{r} \alpha^{*}\left(\operatorname{det}\left(v_{i-1}, v_{i}\right)\right)\left(v_{i-1}-v_{i}\right) .
$$

Equation (2.5) follows from the fact that

$$
\begin{equation*}
\alpha^{*}\left(\operatorname{det}\left(v_{j}, v_{j+1}\right)\right)\left(v_{j}-v_{j+1}\right)=\alpha^{*}\left(\operatorname{det}\left(v_{j}, u\right)\right)\left(v_{j}-u\right)+\alpha^{*}\left(\operatorname{det}\left(u, v_{j+1}\right)\right)\left(u-v_{j+1}\right) . \tag{2.6}
\end{equation*}
$$

Indeed, let $s=\sqrt{\operatorname{det}\left(v_{j}, v_{j+1}\right)}$ and $\phi=\left(v_{j}, v_{j+1}\right) / s \in \mathrm{SL}(2)$. Then,

$$
\begin{equation*}
v_{j}=\phi\left(s e_{1}\right) \text { and } v_{j+1}=\phi\left(s e_{2}\right) \tag{2.7}
\end{equation*}
$$

Since $u \in \operatorname{relint}\left[v_{j}, v_{j+1}\right]$, there exists $\lambda \in(0,1)$ such that $u=\lambda v_{j}+(1-\lambda) v_{j+1}$. Setting $v=\lambda e_{1}+(1-\lambda) e_{2}$, we obtain

$$
\begin{equation*}
u=\phi(s v) . \tag{2.8}
\end{equation*}
$$

Because of (2.7) and (2.8), the right hand side of (2.6) equals

$$
\begin{aligned}
& \phi\left(s \alpha^{*}\left(s^{2}(1-\lambda)\right)\left(e_{1}-v\right)+s \alpha^{*}\left(s^{2} \lambda\right)\left(v-e_{2}\right)\right) \\
= & s \alpha^{*}\left(s^{2}\right) \phi\left(e_{1}-e_{2}\right)=\alpha^{*}\left(\operatorname{det}\left(v_{j}, v_{j+1}\right)\right)\left(v_{j}-v_{j+1}\right),
\end{aligned}
$$

as $v=\lambda e_{1}+(1-\lambda) e_{2}$ and by the additivity property of $\alpha$.
Second, let $0 \in \operatorname{int} P$ and $P=\left[v_{1}, \ldots, v_{r}\right]$ with vertices $\left\{v_{1}, \ldots, v_{r}\right\}$ labeled counterclockwisely. Then, we have

$$
h_{\alpha}(P)=\alpha^{*}\left(\operatorname{det}\left(v_{r}, v_{1}\right)\right)\left(v_{r}-v_{1}\right)+\sum_{i=2}^{r} \alpha^{*}\left(\operatorname{det}\left(v_{i-1}, v_{i}\right)\right)\left(v_{i-1}-v_{i}\right)
$$

(i) Assume $L$ passes through $v_{1}$ and $v_{j}$. Without loss of generality, we have $P \cap L^{+}=$ $\left[0, v_{1}, \ldots, v_{j}\right]$ and $P \cap L^{-}=\left[0, v_{j}, \ldots, v_{r}, v_{1}\right]$. Thus,

$$
h_{\alpha}\left(P \cap L^{+}\right)=\sum_{i=2}^{j} \alpha^{*}\left(\operatorname{det}\left(v_{i-1}, v_{i}\right)\right)\left(v_{i-1}-v_{i}\right)
$$

and

$$
h_{\alpha}\left(P \cap L^{-}\right)=\alpha^{*}\left(\operatorname{det}\left(v_{r}, v_{1}\right)\right)\left(v_{r}-v_{1}\right)+\sum_{i=j+1}^{r} \alpha^{*}\left(\operatorname{det}\left(v_{i-1}, v_{i}\right)\right)\left(v_{i-1}-v_{i}\right)
$$

(ii) Assume $L$ passes through $v_{1}$ and intersects the edge $\left[v_{j}, v_{j+1}\right]$. Without loss of generality, we have $P \cap L^{+}=\left[0, v_{1}, \ldots, v_{j}, u\right]$ and $P \cap L^{-}=\left[0, u, v_{j+1}, \ldots, v_{r}, v_{1}\right]$. Thus,

$$
h_{\alpha}\left(P \cap L^{+}\right)=\alpha^{*}\left(\operatorname{det}\left(v_{j}, u\right)\right)\left(v_{j}-u\right)+\sum_{i=2}^{j} \alpha^{*}\left(\operatorname{det}\left(v_{i-1}, v_{i}\right)\right)\left(v_{i-1}-v_{i}\right)
$$

and
$h_{\alpha}\left(P \cap L^{-}\right)=\alpha^{*}\left(\operatorname{det}\left(v_{r}, v_{1}\right)\right)\left(v_{r}-v_{1}\right)+\alpha^{*}\left(\operatorname{det}\left(u, v_{j+1}\right)\right)\left(u-v_{j+1}\right)+\sum_{i=j+2}^{r} \alpha^{*}\left(\operatorname{det}\left(v_{i-1}, v_{i}\right)\right)\left(v_{i-1}-v_{i}\right)$.
Equation (2.5) follows from (2.6).
(iii) Assume $L$ intersects the edge $\left[v_{r}, v_{1}\right]$ at $u_{1}$ and the edge $\left[v_{j}, v_{j+1}\right]$ at $u_{2}$. Without loss of generality, we have $P \cap L^{+}=\left[0, u_{1}, v_{1}, \ldots, v_{j}, u_{2}\right]$ and $P \cap L^{-}=\left[0, u_{2}, v_{j+1}, \ldots, v_{r}, u_{1}\right]$. Thus,
$h_{\alpha}\left(P \cap L^{+}\right)=\alpha^{*}\left(\operatorname{det}\left(u_{1}, v_{1}\right)\right)\left(u_{1}-v_{1}\right)+\alpha^{*}\left(\operatorname{det}\left(v_{j}, u_{2}\right)\right)\left(v_{j}-u_{2}\right)+\sum_{i=2}^{j} \alpha^{*}\left(\operatorname{det}\left(v_{i-1}, v_{i}\right)\right)\left(v_{i-1}-v_{i}\right)$
and
$h_{\alpha}\left(P \cap L^{-}\right)=\alpha^{*}\left(\operatorname{det}\left(v_{r}, u_{1}\right)\right)\left(v_{r}-u_{1}\right)+\alpha^{*}\left(\operatorname{det}\left(u_{2}, v_{j+1}\right)\right)\left(u_{2}-v_{j+1}\right)+\sum_{i=j+2}^{r} \alpha^{*}\left(\operatorname{det}\left(v_{i-1}, v_{i}\right)\right)\left(v_{i-1}-v_{i}\right)$.
Equation (2.5) follows from an analog of (2.6).

## $3 \mathrm{SL}(n)$ covariant valuations on $\mathcal{P}_{0}^{n}$

### 3.1 The two-dimensional case

First, we give the representation of such valuations on $s T^{2}$ for $s>0$.
Lemma 3.1. If $\mu: \mathcal{P}_{0}^{2} \rightarrow \mathbb{R}^{2}$ is an $\mathrm{SL}(2)$ covariant valuation, then there exist constants $c_{1}, c_{2} \in \mathbb{R}$ and a solution of Cauchy's functional equation $\alpha:[0, \infty) \rightarrow \mathbb{R}$ such that

$$
\mu\left(s T^{2}\right)=c_{1} m\left(s T^{2}\right)+c_{2} s\left(e_{1}+e_{2}\right)+\frac{\alpha\left(s^{2}\right)}{s}\left(e_{1}-e_{2}\right)
$$

for $s>0$.

Proof. First, we decompose $\mu$ as $\mu=\mu^{+}+\mu^{-}$, where $\mu^{+}$is an $\mathrm{SL}^{ \pm}(2)$ covariant valuation and $\mu^{-}$is an $\mathrm{SL}^{ \pm}(2)$ signum covariant one.

Next, let $v=\left(v_{1}, v_{2}\right)^{t} \in \mathbb{R}^{2}$ with $v_{1} v_{2} \neq 0$,

$$
\rho_{1}=\left(\begin{array}{cc}
v_{1} & 0 \\
v_{2} & 1 / v_{1}
\end{array}\right), \rho_{2}=\left(\begin{array}{cc}
v_{1} & 0 \\
v_{2} & -1 / v_{1}
\end{array}\right) \text { and } \rho_{3}=\left(\begin{array}{cc}
v_{1} & -1 / v_{2} \\
v_{2} & 0
\end{array}\right) .
$$

Then, we have $v=\rho_{1} e_{1}=\rho_{2} e_{1}$. The $\mathrm{SL}^{ \pm}(2)$ covariance of $\mu^{+}$implies

$$
\begin{aligned}
\mu^{+}([0, v]) & =\mu^{+}\left(\rho_{1} T^{1}\right)=\rho_{1} \mu^{+}\left(T^{1}\right) \\
& =\mu^{+}\left(\rho_{2} T^{1}\right)=\rho_{2} \mu^{+}\left(T^{1}\right)
\end{aligned}
$$

Setting $\mu^{+}\left(T^{1}\right)=\left(x_{1}^{+}, x_{2}^{+}\right)^{t}$, we obtain

$$
\begin{aligned}
v_{1} x_{1}^{+} & =v_{1} x_{1}^{+} \\
v_{2} x_{1}^{+}+x_{2}^{+} / v_{1} & =v_{2} x_{1}^{+}-x_{2}^{+} / v_{1}
\end{aligned}
$$

Thus, $x_{2}^{+}=0$ and there exists a constant $c \in \mathbb{R}$ such that $\mu^{+}\left(T^{1}\right)=c e_{1}$. For $s>0$, we apply

$$
\rho_{0}=\left(\begin{array}{cc}
s & 0 \\
0 & 1 / s
\end{array}\right)
$$

and get

$$
\begin{equation*}
\mu^{+}\left(s T^{1}\right)=\mu^{+}\left(\rho_{0} T^{1}\right)=\rho_{0} \mu^{+}\left(T^{1}\right)=c s e_{1} . \tag{3.1}
\end{equation*}
$$

On the other hand, the $\mathrm{SL}^{ \pm}(2)$ signum covariance of $\mu^{-}$implies

$$
\begin{aligned}
\mu^{-}([0, v]) & =\mu^{-}\left(\rho_{1} T^{1}\right)=\rho_{1} \mu^{-}\left(T^{1}\right) \\
& =\mu^{-}\left(\rho_{2} T^{1}\right)=-\rho_{2} \mu^{-}\left(T^{1}\right) \\
& =\mu^{-}\left(\rho_{3} T^{1}\right)=\rho_{3} \mu^{-}\left(T^{1}\right) .
\end{aligned}
$$

Setting $\mu^{-}\left(T^{1}\right)=\left(x_{1}^{-}, x_{2}^{-}\right)^{t}$, we obtain

$$
\begin{aligned}
v_{1} x_{1}^{-} & =-v_{1} x_{1}^{-}=v_{1} x_{1}^{-}-x_{2}^{-} / v_{2} \\
v_{2} x_{1}^{-}+x_{2}^{-} / v_{1} & =-v_{2} x_{1}^{-}+x_{2}^{-} / v_{1}=v_{2} x_{1}^{-}
\end{aligned}
$$

Thus, $x_{1}^{-}=x_{2}^{-}=0$, which implies $\mu^{-}\left(T^{1}\right)=0$. Similarly, we get

$$
\begin{equation*}
\mu^{-}\left(s T^{1}\right)=0 \tag{3.2}
\end{equation*}
$$

for $s>0$ and

$$
\begin{equation*}
\mu([0, v])=\rho_{1}\left(\mu^{+}\left(T^{1}\right)+\mu^{-}\left(T^{1}\right)\right)=c v \tag{3.3}
\end{equation*}
$$

Finally, we use the dissection in Definition 2. It follows from (2.4) and (3.1) that, for $s>0$,

$$
\mu^{+}\left(\sqrt{s} T^{2}\right)+c \sqrt{s}(\lambda, 1-\lambda)^{t}=\sqrt{\lambda}^{-1} \phi_{2} \mu^{+}\left(\sqrt{\lambda s} T^{2}\right)+\sqrt{1-\lambda}^{-1} \psi_{2} \mu^{+}\left(\sqrt{(1-\lambda) s} T^{2}\right)
$$

Setting $\lambda=a /(a+b)$ and $s=a+b$ for $a, b>0$, we have

$$
\frac{1}{\sqrt{a+b}} \mu^{+}\left(\sqrt{a+b} T^{2}\right)+\frac{c}{a+b}(a, b)^{t}=\frac{1}{\sqrt{a}} \phi_{2} \mu^{+}\left(\sqrt{a} T^{2}\right)+\frac{1}{\sqrt{b}} \psi_{2} \mu^{+}\left(\sqrt{b} T^{2}\right)
$$

Write $g^{+}(x)=\mu^{+}\left(\sqrt{x} T^{2}\right) / \sqrt{x}=\left(g_{1}^{+}(x), g_{2}^{+}(x)\right)^{t}$ for $x>0$. Then, the equation above becomes

$$
\begin{align*}
& g_{1}^{+}(a+b)+\frac{c a}{a+b}=\frac{a}{a+b} g_{1}^{+}(a)+g_{1}^{+}(b)+\frac{a}{a+b} g_{2}^{+}(b), \\
& g_{2}^{+}(a+b)+\frac{c b}{a+b}=\frac{b}{a+b} g_{1}^{+}(a)+g_{2}^{+}(a)+\frac{b}{a+b} g_{2}^{+}(b) \tag{3.4}
\end{align*}
$$

and equivalently

$$
\begin{aligned}
g_{1}^{+}(a+b)+g_{2}^{+}(a+b)+c & =g_{1}^{+}(a)+g_{2}^{+}(a)+g_{1}^{+}(b)+g_{2}^{+}(b), \\
b\left(g_{1}^{+}(a+b)-g_{1}^{+}(b)\right) & =a\left(g_{2}^{+}(a+b)-g_{2}^{+}(a)\right) .
\end{aligned}
$$

Moreover, applying

$$
\sigma=\left(\begin{array}{ll}
0 & 1 \\
1 & 0
\end{array}\right)
$$

we have $\mu^{+}\left(s T^{2}\right)=\mu^{+}\left(\sigma s T^{2}\right)=\sigma \mu^{+}\left(s T^{2}\right)$. Hence, $\mu_{1}^{+}\left(s T^{2}\right)=\mu_{2}^{+}\left(s T^{2}\right)$, which implies $g_{1}^{+}=$ $g_{2}^{+}$. Consequently,

$$
\begin{aligned}
g_{1}^{+}(a+b)+c / 2 & =g_{1}^{+}(a)+g_{1}^{+}(b) \\
b\left(g_{1}^{+}(a+b)-g_{1}^{+}(b)\right) & =a\left(g_{1}^{+}(a+b)-g_{1}^{+}(a)\right)
\end{aligned}
$$

It follows that

$$
\begin{equation*}
g_{1}^{+}(x)=\gamma(x)+c / 2 \quad \text { for } x>0 \tag{3.5}
\end{equation*}
$$

where $\gamma:[0, \infty] \rightarrow \mathbb{R}$ is a solution of Cauchy's functional equation. Inserting (3.5) into (3.4), we see that $\gamma$ is linear, i.e. there exist constants $c_{1}^{\prime}, c_{2} \in \mathbb{R}$ such that $g_{1}^{+}(x)=g_{2}^{+}(x)=c_{1}^{\prime} x+c_{2}$, where $c_{2}=c / 2$. Therefore

$$
\begin{equation*}
\mu^{+}\left(s T^{2}\right)=c_{1}^{\prime} s^{3}\left(e_{1}+e_{2}\right)+c_{2} s\left(e_{1}+e_{2}\right)=c_{1} m\left(s T^{2}\right)+c_{2} s\left(e_{1}+e_{2}\right), \tag{3.6}
\end{equation*}
$$

where $c_{1}=6 c_{1}^{\prime}$ and in the second step we use $m\left(s T^{2}\right)=s^{3}\left(e_{1}+e_{2}\right) / 3$ !.

On the other hand, by (2.4) and (3.2), we obtain

$$
\mu^{-}\left(\sqrt{s} T^{2}\right)=\sqrt{\lambda}^{-1} \phi_{2} \mu^{-}\left(\sqrt{\lambda s} T^{2}\right)+\sqrt{1-\lambda}^{-1} \psi_{2} \mu^{-}\left(\sqrt{(1-\lambda) s} T^{2}\right)
$$

By putting $\lambda=a /(a+b)$ and $s=a+b$ for $a, b>0$, we obtain

$$
\frac{1}{\sqrt{a+b}} \mu^{-}\left(\sqrt{a+b} T^{2}\right)=\frac{1}{\sqrt{a}} \phi_{2} \mu^{-}\left(\sqrt{a} T^{2}\right)+\frac{1}{\sqrt{b}} \psi_{2} \mu^{-}\left(\sqrt{b} T^{2}\right) .
$$

Write $g^{-}(x)=\mu^{-}\left(\sqrt{x} T^{2}\right) / \sqrt{x}=\left(g_{1}^{-}(x), g_{2}^{-}(x)\right)^{t}$ for $x>0$. Then, the equation above becomes

$$
\begin{aligned}
g_{1}^{-}(a+b)+g_{2}^{-}(a+b) & =g_{1}^{-}(a)+g_{2}^{-}(a)+g_{1}^{-}(b)+g_{2}^{-}(b) \\
b\left(g_{1}^{-}(a+b)-g_{1}^{-}(b)\right) & =a\left(g_{2}^{-}(a+b)-g_{2}^{-}(a)\right) .
\end{aligned}
$$

Moreover, applying $\sigma$ again, we have $\mu^{-}\left(s T^{2}\right)=\mu^{-}\left(\sigma s T^{2}\right)=-\sigma \mu^{-}\left(s T^{2}\right)$. Then $\mu_{1}^{-}\left(s T^{2}\right)+$ $\mu_{2}^{-}\left(s T^{2}\right)=0$, which implies $g_{1}^{-}(s)+g_{2}^{-}(s)=0$. This implies

$$
(a+b) g_{1}^{-}(a+b)=a g_{1}^{-}(a)+b g_{1}^{-}(b)
$$

Therefore, $g_{1}^{-}(x)=-g_{2}^{-}(x)=\alpha(x) / x$, where $\alpha:[0, \infty) \rightarrow \mathbb{R}$ is a solution of Cauchy's functional equation. It follows that

$$
\begin{equation*}
\mu^{-}\left(s T^{2}\right)=\frac{\alpha\left(s^{2}\right)}{s}\left(e_{1}-e_{2}\right) . \tag{3.7}
\end{equation*}
$$

Combining (3.6) and (3.7) completes the proof.
Next, we consider the valuation on triangles with one vertex at the origin. Let $P=[0, v, w]$ with determinant $\operatorname{det}(v, w)>0$. Set $\phi=(v, w) \in \operatorname{GL}(2)$ such that $\phi e_{1}=v$ and $\phi e_{2}=w$. By Lemma 3.1, there exist constants $c_{1}, c_{2} \in \mathbb{R}$ and a solution of Cauchy's functional equation $\alpha:[0, \infty) \rightarrow \mathbb{R}$ such that

$$
\begin{align*}
\mu(P)=\mu\left(\phi T^{2}\right) & =\sqrt{\operatorname{det}(v, w)}^{-1} \phi \mu\left(\sqrt{\operatorname{det}(v, w)} T^{2}\right) \\
& =c_{1} m(P)+c_{2}(v+w)+\frac{\alpha(\operatorname{det}(v, w))}{\operatorname{det}(v, w)}(v-w) \tag{3.8}
\end{align*}
$$

where in the last step we use that $m(\phi P)=|\operatorname{det} \phi| \phi m(P)$ for $\phi \in \mathrm{GL}(2)$.
Lemma 3.2. If $\mu: \mathcal{P}_{0}^{2} \rightarrow \mathbb{R}^{2}$ is an $\mathrm{SL}(2)$ covariant valuation, then there exist constants $c_{1}, c_{2} \in \mathbb{R}$ and a solution of Cauchy's functional equation $\alpha:[0, \infty) \rightarrow \mathbb{R}$ such that

$$
\mu(P)=c_{1} m(P)+c_{2} e(P)+h_{\alpha}(P)
$$

for every $P \in \mathcal{P}_{0}^{2}$ with $\operatorname{dim} P=2$.

Proof. First, assume that the origin is a vertex of $P$. Let $P=\left[0, v_{1}, v_{2}, \ldots, v_{r}\right]$ be a polygon which has edges $\left[0, v_{1}\right],\left[v_{1}, v_{2}\right], \ldots,\left[v_{r-1}, v_{r}\right],\left[v_{r}, 0\right]$ labeled counter-clockwisely. Triangulate $P$ into the simplices $\left[0, v_{1}, v_{2}\right],\left[0, v_{2}, v_{3}\right], \ldots,\left[0, v_{r-1}, v_{r}\right]$. By the inclusion-exclusion principle, (3.3) and (3.8), there exist constants $c_{1}, c_{2} \in \mathbb{R}$ and a solution of Cauchy's functional equation $\alpha:[0, \infty) \rightarrow \mathbb{R}$ such that

$$
\begin{align*}
\mu(P) & =\mu\left(\left[0, v_{1}, v_{2}\right]\right)+\cdots+\mu\left(\left[0, v_{r-1}, v_{r}\right]\right)-\mu\left(\left[0, v_{2}\right]\right)-\cdots-\mu\left(\left[0, v_{r-1}\right]\right) \\
& =c_{1} m(P)+c_{2}\left(v_{1}+v_{r}\right)+\sum_{i=2}^{r} \frac{\alpha\left(\operatorname{det}\left(v_{i-1}, v_{i}\right)\right)}{\operatorname{det}\left(v_{i-1}, v_{i}\right)}\left(v_{i-1}-v_{i}\right) . \tag{3.9}
\end{align*}
$$

Second, assume that the origin is contained in the relative interior of an edge of $P$. Let $P=\left[v_{1}, \ldots, v_{r}\right]$ with $0 \in \operatorname{relint}\left[v_{1}, v_{r}\right]$ and $\left[v_{1}, v_{2}\right], \ldots,\left[v_{r-1}, v_{r}\right],\left[v_{r}, v_{1}\right]$ labeled counterclockwisely. Triangulate $P$ into simplices $\left[0, v_{1}, v_{2}\right],\left[0, v_{2}, v_{3}\right], \ldots,\left[0, v_{r-1}, v_{r}\right]$. By the inclusionexclusion principle, (3.3) and (3.8), we obtain

$$
\begin{align*}
\mu(P) & =\mu\left(\left[0, v_{1}, v_{2}\right]\right)+\cdots+\mu\left(\left[0, v_{r-1}, v_{r}\right]\right)-\mu\left(\left[0, v_{2}\right]\right)-\cdots-\mu\left(\left[0, v_{r-1}\right]\right) \\
& =c_{1} m(P)+c_{2}\left(v_{1}+v_{r}\right)+\sum_{i=2}^{r} \frac{\alpha\left(\operatorname{det}\left(v_{i-1}, v_{i}\right)\right)}{\operatorname{det}\left(v_{i-1}, v_{i}\right)}\left(v_{i-1}-v_{i}\right) \tag{3.10}
\end{align*}
$$

Third, assume that $0 \in \operatorname{int} P$. Let $P=\left[v_{1}, v_{2}, \ldots, v_{r}\right]$ be such a polygon which has edges $\left[v_{1}, v_{2}\right], \ldots,\left[v_{r-1}, v_{r}\right]$ labeled counter-clockwisely. Triangulate $P$ into simplices $\left[0, v_{1}, v_{2}\right]$, $\left[0, v_{2}, v_{3}\right], \ldots,\left[0, v_{r-1}, v_{r}\right],\left[0, v_{r}, v_{1}\right]$. By the inclusion-exclusion principle, (3.3) and (3.8), we have

$$
\begin{align*}
\mu(P)= & \mu\left(\left[0, v_{1}, v_{2}\right]\right)+\cdots+\mu\left(\left[0, v_{r-1}, v_{r}\right]\right)+\mu\left(\left[0, v_{r}, v_{1}\right]\right) \\
& -\mu\left(\left[0, v_{1}\right]\right)-\mu\left(\left[0, v_{2}\right]\right)-\cdots-\mu\left(\left[0, v_{r}\right]\right)  \tag{3.11}\\
= & c_{1} m(P)+\frac{\alpha\left(\operatorname{det}\left(v_{r}, v_{1}\right)\right)}{\operatorname{det}\left(v_{r}, v_{1}\right)}\left(v_{r}-v_{1}\right)+\sum_{i=2}^{r} \frac{\alpha\left(\operatorname{det}\left(v_{i-1}, v_{i}\right)\right)}{\operatorname{det}\left(v_{i-1}, v_{i}\right)}\left(v_{i-1}-v_{i}\right) .
\end{align*}
$$

Combining (3.9), (3.10), (3.11) and the definitions of $e$ and $h_{\alpha}$ on $\mathcal{P}_{0}^{2}$ we completes the proof.

Using $\mu(\{0\})=0$, (3.3), Lemma 2.4, Lemma 2.5 and Lemma 3.2, we complete the proof of Theorem 1.5.

Finally, we consider measurable $\mathrm{SL}(2)$ covariant valuations. Define the functional $h$ : $\mathcal{P}_{0}^{2} \rightarrow \mathbb{R}^{2}$ by

$$
h(P)=v_{1}-v_{r}
$$

if $\operatorname{dim} P=2$ and $P=\left[0, v_{1}, \ldots, v_{r}\right]$ with $0 \in \operatorname{bd} P$ and the vertices $\left\{0, v_{1}, \ldots, v_{r}\right\}$ labeled counter-clockwisely;

$$
h(P)=0
$$

if $0 \in \operatorname{int} P$ or $P$ is a line segment or $P=\{0\}$.
If we assume that $h_{\alpha}$ is a measurable and $\mathrm{SL}(2)$ covariant valuation, then $\alpha$ is linear. There exists a constant $c_{3}$ such that $h_{\alpha}(P)=c_{3} h(P)$. Because $h_{\alpha}$ is a simple valuation, we know that $h$ is also a simple valuation on $\mathcal{P}_{0}^{2}$. Using Theorem 1.5, we obtain Corollary 1.1.

### 3.2 The higher-dimensional case

In this section, we first give the following propositions about simplices containing the origin.
Proposition 3.1. Let $n \geq 3$. If $\mu: \mathcal{P}_{0}^{n} \rightarrow \mathbb{R}^{n}$ is an $\mathrm{SL}(n)$ covariant valuation, then there exists a constant $a \in \mathbb{R}$ such that $\mu\left(T^{n}\right)=a \mathbf{1}$.

Proof. We first consider $\mu\left(T^{3}\right)$. Write $\mu\left(T^{3}\right)=\left(x_{1}, x_{2}, x_{3}\right)^{t}$ and

$$
\sigma_{0}=\left(\begin{array}{lll}
0 & 0 & 1 \\
1 & 0 & 0 \\
0 & 1 & 0
\end{array}\right)
$$

The SL(3) covariance of $\mu$ implies

$$
\mu\left(T^{3}\right)=\mu\left(\sigma_{0} T^{3}\right)=\sigma_{0} \mu\left(T^{3}\right)=\left(\begin{array}{lll}
0 & 0 & 1 \\
1 & 0 & 0 \\
0 & 1 & 0
\end{array}\right)\left(\begin{array}{l}
x_{1} \\
x_{2} \\
x_{3}
\end{array}\right)=\left(\begin{array}{l}
x_{3} \\
x_{1} \\
x_{2}
\end{array}\right) .
$$

Thus, $x_{1}=x_{2}=x_{3}$.
Next, we consider $\mu\left(T^{n}\right)$ for $n \geq 4$ by a similar argument. Write $\mu\left(T^{n}\right)=\left(x_{1}, \ldots, x_{n}\right)^{t}$ and

$$
\sigma=\left(\begin{array}{ccc}
I_{r} & & \\
& \sigma_{0} & \\
& & I_{n-r-3}
\end{array}\right) \in \mathrm{SL}(n)
$$

where $r=0,1, \ldots, n-3$ and $\sigma_{0}$ moves along the main diagonal of $\sigma$. Using the $\operatorname{SL}(n)$ covariance of $\mu$, we have $\mu\left(T^{n}\right)=\mu\left(\sigma T^{n}\right)=\sigma \mu\left(T^{n}\right)$. This yields $x_{1}=\cdots=x_{n}$. Thus, $\mu\left(T^{n}\right)=a \mathbf{1}$ with $a=x_{1}$.

Proposition 3.2. If $\mu: \mathcal{P}_{0}^{3} \rightarrow \mathbb{R}^{3}$ is an $\mathrm{SL}(3)$ covariant valuation, then there exists $a$ constant $c \in \mathbb{R}$ such that $\mu\left(T^{1}\right)=2 c e_{1}$ and $\mu\left(T^{2}\right)=c\left(e_{1}+e_{2}\right)$.

Proof. Write $\mu\left(T^{1}\right)=\left(x_{1}, x_{2}, x_{3}\right)^{t}$ and $\mu\left(T^{2}\right)=\left(y_{1}, y_{2}, y_{3}\right)^{t}$. Set

$$
\sigma_{1}=\left(\begin{array}{ccc}
1 & 0 & 0 \\
0 & -1 & 0 \\
0 & 0 & -1
\end{array}\right) \text { and } \sigma_{2}=\left(\begin{array}{ccc}
0 & 1 & 0 \\
1 & 0 & 0 \\
0 & 0 & -1
\end{array}\right)
$$

The $\operatorname{SL}(n)$ covariance of $\mu$ implies that $\mu\left(T^{1}\right)=\mu\left(\sigma_{1} T^{1}\right)=\sigma_{1} \mu\left(T^{1}\right)$ and $\mu\left(T^{2}\right)=\mu\left(\sigma_{2} T^{2}\right)=$ $\sigma_{2} \mu\left(T^{2}\right)$. Thus, we have $\mu\left(T^{1}\right)=\left(x_{1}, 0,0\right)^{t}$ and $\mu\left(T^{2}\right)=\left(y_{1}, y_{1}, 0\right)^{t}$.

Now, we use the dissection in Definition 1. Then, equation (2.2) is equivalent to

$$
\left(\begin{array}{ccc}
\lambda & \lambda & 0 \\
1-\lambda & 1-\lambda & 0 \\
0 & 0 & \frac{1}{\lambda}+\frac{1}{1-\lambda}-1
\end{array}\right)\left(\begin{array}{l}
y_{1} \\
y_{1} \\
0
\end{array}\right)=\left(\begin{array}{ccc}
\lambda & 0 & 0 \\
1-\lambda & 1 & 0 \\
0 & 0 & \frac{1}{\lambda}
\end{array}\right)\left(\begin{array}{l}
x_{1} \\
0 \\
0
\end{array}\right)
$$

This yields $x_{1}=2 y_{1}$. Therefore, there exists a constant $c$ such that $\mu\left(T^{1}\right)=2 c e_{1}$ and $\mu\left(T^{2}\right)=c\left(e_{1}+e_{2}\right)$.

From now on, we investigate $\mathrm{SL}(n)$ covariant valuations on $\mathcal{T}^{k}$ for the three-dimensional case and the $n$-dimensional case for $n \geq 4$, respectively.

Lemma 3.3. If $\mu: \mathcal{P}_{0}^{3} \rightarrow \mathbb{R}^{3}$ is an $\mathrm{SL}(3)$ covariant valuation, then $\mu$ is simple.
Proof. Note that for $k \leq 2$, every simplex $T \in \mathcal{T}^{k}$ is an $\mathrm{SL}(3)$ image of $T^{k}$. Thus, it suffices to prove that $\mu$ vanishes on the standard simplices $\{0\}, T^{1}$ and $T^{2}$.

First, let $\mu(\{0\})=\left(x_{1}, x_{2}, x_{3}\right)^{t}$ and $\sigma_{1}$ be the same as in the proof of Proposition 3.2 while

$$
\sigma=\left(\begin{array}{ccc}
-1 & 0 & 0 \\
0 & -1 & 0 \\
0 & 0 & 1
\end{array}\right)
$$

Using the SL(3) covariance of $\mu$, we have

$$
\begin{aligned}
\mu(\{0\}) & =\mu(\sigma\{0\})=\sigma \mu(\{0\}) \\
& =\mu\left(\sigma_{1}\{0\}\right)=\sigma_{1} \mu(\{0\}) .
\end{aligned}
$$

This yields $x_{1}=x_{2}=x_{3}=0$. Therefore $\mu(\{0\})=0$.
Next, let $T_{23}=\left[0, e_{2}, e_{3}\right]$ and $\sigma_{0}$ be the same as in the proof of Proposition 3.1. It follows from $T_{23}=\sigma_{0} T^{2}$ and Proposition 3.2 that

$$
\mu\left(T_{23}\right)=\mu\left(\sigma_{0} T^{2}\right)=\sigma_{0} \mu\left(T^{2}\right)=c\left(e_{2}+e_{3}\right) .
$$

Setting

$$
\rho=\left(\begin{array}{ccc}
s^{-2} & 0 & 0 \\
0 & s & 0 \\
0 & 0 & s
\end{array}\right)
$$

we obtain

$$
\begin{equation*}
\mu\left(s T_{23}\right)=\mu\left(\rho T_{23}\right)=\rho \mu\left(T_{23}\right)=c s\left(e_{2}+e_{3}\right) \tag{3.12}
\end{equation*}
$$

for every $s>0$.
Finally, we use the dissection in Definition 2. By (2.4) and (3.12), it follows that

$$
\mu\left(\sqrt[3]{s} T^{3}\right)+c \sqrt[3]{s}(\lambda, 1-\lambda, 1)^{t}=\lambda^{-1 / 3} \phi_{2} \mu\left(\sqrt[3]{\lambda s} T^{3}\right)+(1-\lambda)^{-1 / 3} \psi_{2} \mu\left(\sqrt[3]{(1-\lambda) s} T^{3}\right)
$$

We set $\lambda=a /(a+b)$ and $s=a+b$ for $a, b>0$ to get

$$
\frac{1}{\sqrt[3]{a+b}} \mu\left(\sqrt[3]{a+b} T^{3}\right)+\frac{c}{a+b}(a, b, a+b)^{t}=\frac{1}{\sqrt[3]{a}} \phi_{2} \mu\left(\sqrt[3]{a} T^{3}\right)+\frac{1}{\sqrt[3]{b}} \psi_{2} \mu\left(\sqrt[3]{b} T^{3}\right) .
$$

Write $g(x)=\mu\left(\sqrt[3]{x} T^{3}\right) / \sqrt[3]{x}=\left(g_{1}(x), g_{2}(x), g_{3}(x)\right)^{t}$ for $x>0$. Now, the equation above is equivalent to

$$
\begin{align*}
g_{1}(a+b)+g_{2}(a+b)+c & =g_{1}(a)+g_{2}(a)+g_{1}(b)+g_{2}(b),  \tag{3.13}\\
g_{3}(a+b)+c & =g_{3}(a)+g_{3}(b) .
\end{align*}
$$

By Proposition 3.1, we obtain $g_{1}(x)=g_{2}(x)=g_{3}(x)$. Thus, (3.13) yields

$$
\begin{aligned}
g_{1}(a+b)+c / 2 & =g_{1}(a)+g_{1}(b), \\
g_{1}(a+b)+c & =g_{1}(a)+g_{1}(b) .
\end{aligned}
$$

Therefore, $c=0$.
Lemma 3.4. Let $n \geq 4$. If $\mu: \mathcal{P}_{0}^{n} \rightarrow \mathbb{R}^{n}$ is an $\mathrm{SL}(n)$ covariant valuation, then $\mu$ is simple.
Proof. Notice that for $k \leq n-1$, every simplex $T \in \mathcal{T}^{k}$ is an $\operatorname{SL}(n)$ image of $T^{n}$. It suffices to prove that $\mu$ vanishes on the standard simplex $T^{k}$. We prove the statement by induction on $k=\operatorname{dim} T$.

For $k=0$, let $\mu(\{0\})=\left(w_{1}, \ldots, w_{n}\right)^{t}$,

$$
\sigma=\left(\begin{array}{cc}
-1 & 0 \\
0 & -1
\end{array}\right) \text { and } \sigma_{1}=\left(\begin{array}{ccc}
I_{r} & & \\
& \sigma & \\
& & I_{n-r-2}
\end{array}\right) \in \mathrm{SL}(n)
$$

where $r=0,1, \ldots, n-2$ and $\sigma$ moves along the main diagonal of $\sigma_{1}$. Using the $\operatorname{SL}(n)$ covariance of $\mu$, we have $\mu(\{0\})=\mu\left(\sigma_{1}\{0\}\right)=\sigma_{1} \mu(\{0\})$. Therefore, $w_{1}=\cdots=w_{n}=0$.

For $k=1$, let $\mu\left(T^{1}\right)=\left(v_{1}, \ldots, v_{n}\right)^{t}$ and

$$
\sigma_{3}=\left(\begin{array}{ccc}
I_{l} & & \\
& \sigma & \\
& & I_{n-l-2}
\end{array}\right) \in \mathrm{SL}(n)
$$

where $l=1, \ldots, n-2$ and $\sigma$ moves along the main diagonal of $\sigma_{3}$. Using the $\mathrm{SL}(n)$ covariance of $\mu$, we obtain $\mu\left(T^{1}\right)=\mu\left(\sigma_{3} T^{1}\right)=\sigma_{3} \mu\left(T^{1}\right)$. Therefore $v_{2}=\cdots=v_{n}=0$ and there exists a constant $c$ such that $\mu\left(T^{1}\right)=2 c e_{1}$.

For $k=2$, let $\mu\left(T^{2}\right)=\left(x_{1}, \ldots, x_{n}\right)^{t}$,

$$
\sigma_{4}=\left(\begin{array}{cc}
\sigma_{2} & 0 \\
0 & I_{n-3}
\end{array}\right) \text { and } \sigma_{5}=\left(\begin{array}{ccc}
I_{r} & & \\
& \sigma & \\
& & I_{n-r-2}
\end{array}\right) \in \operatorname{SL}(n)
$$

where $r=2, \ldots, n-2, \sigma_{2}$ is the same as in the proof of Proposition 3.2 and $\sigma$ moves along the main diagonal of $\sigma_{5}$. By the $\operatorname{SL}(n)$ covariance of $\mu$, we have $\mu\left(T^{2}\right)=\mu\left(\sigma_{4} T^{2}\right)=\sigma_{4} \mu\left(T^{2}\right)$ and $\mu\left(T^{2}\right)=\mu\left(\sigma_{5} T^{2}\right)=\sigma_{5} \mu\left(T^{2}\right)$. Therefore, $x_{1}=x_{2}$ and $x_{3}=\cdots=x_{n}=0$. We use the dissection in Definition 1. Then, (2.2) is equivalent to

$$
\left(\begin{array}{ccccc}
\lambda & \lambda & 0 & \cdots & 0 \\
1-\lambda & 1-\lambda & 0 & \cdots & 0 \\
0 & 0 & 1 & \cdots & 0 \\
\cdots & \cdots & \cdots & \cdots & \cdots \\
0 & 0 & 0 & \cdots & \frac{1}{\lambda}+\frac{1}{1-\lambda}-1
\end{array}\right)\left(\begin{array}{l}
x_{1} \\
x_{1} \\
0 \\
\cdots \\
0
\end{array}\right)=\left(\begin{array}{ccccc}
\lambda & 0 & 0 & \cdots & 0 \\
1-\lambda & 1 & 0 & \cdots & 0 \\
0 & 0 & 1 & \cdots & 0 \\
\cdots & \cdots & \cdots & \cdots & \cdots \\
0 & 0 & 0 & \cdots & \frac{1}{\lambda}
\end{array}\right)\left(\begin{array}{l}
2 c \\
0 \\
0 \\
\cdots \\
0
\end{array}\right) .
$$

This yields $x_{1}=c$. Moreover, we know that $\mu\left(T^{2}\right)=c\left(e_{1}+e_{2}\right)$ and $\mu\left(\left[0, e_{2}, e_{3}\right]\right)=c\left(e_{2}+e_{3}\right)$.
For $k=3$, let $\mu\left(T^{3}\right)=\left(y_{1}, \ldots, y_{n}\right)^{t}$,

$$
\sigma_{6}=\left(\begin{array}{cc}
\sigma_{0} & 0 \\
0 & I_{n-3}
\end{array}\right) \text { and } \sigma_{7}=\left(\begin{array}{ccc}
I_{q} & & \\
& \sigma & \\
& & I_{n-q-2}
\end{array}\right) \in \operatorname{SL}(n)
$$

where $q=3, \ldots, n-2, \sigma_{0}$ is the same as in the proof of Proposition 3.1 and $\sigma$ moves along the main diagonal of $\sigma_{7}$. By the $\operatorname{SL}(n)$ covariance of $\mu$, we have $\mu\left(T^{3}\right)=\mu\left(\sigma_{6} T^{3}\right)=\sigma_{6} \mu\left(T^{3}\right)$ and $\mu\left(T^{3}\right)=\mu\left(\sigma_{7} T^{3}\right)=\sigma_{7} \mu\left(T^{3}\right)$. This yields $y_{1}=y_{2}=y_{3}$ and $y_{4}=\cdots=y_{n}=0$.

For $T^{3}$, we take the same dissection as above and similarly obtain $y_{1}=c=0$. Therefore, $\mu\left(T^{1}\right)=\mu\left(T^{2}\right)=\mu\left(T^{3}\right)=0$.

Next, assume that $\mu(T)=0$ for all $T$ with $\operatorname{dim} T \leq k-1$ and $k \geq 4$. We are going to prove the statement for $\operatorname{dim} T=k \leq n-1$. By the induction hypothesis, we know that $\mu\left(T^{k-1}\right)=0$. Let $\mu\left(T^{k}\right)=\left(z_{1}, \ldots, z_{n}\right)^{t}$,

$$
\sigma_{8}=\left(\begin{array}{cccc}
I_{r} & & & \\
& \sigma_{0} & & \\
& & I_{k-r-3} & \\
& & & I_{n-k}
\end{array}\right) \text { and } \sigma_{9}=\left(\begin{array}{cccc}
I_{k} & & & \\
& I_{l} & & \\
& & \sigma & \\
& & & I_{k-l-2}
\end{array}\right)
$$

where $r=0,1, \ldots, k-3, l=0, \ldots, n-k-2$ and $\sigma, \sigma_{0}$ moves along the main diagonal of $\sigma_{8}$ and $\sigma_{9}$, respectively. By the $\operatorname{SL}(n)$ covariance, we have $\mu\left(T^{k}\right)=\mu\left(\sigma_{8} T^{k}\right)=\sigma_{8} \mu\left(T^{k}\right)$ and $\mu\left(T^{k}\right)=\mu\left(\sigma_{9} T^{k}\right)=\sigma_{9} \mu\left(T^{k}\right)$. Therefore, $z_{1}=\cdots=z_{k}$ and $z_{k+1}=\cdots=z_{n}=0$. Now, we use a dissection which is slightly different from Definition 1 . Denote by $H_{\lambda}$ the hyperplane through the origin with the normal vector $(1-\lambda) e_{k-1}-\lambda e_{k}$. Define $\phi \in \operatorname{SL}(n)$ by

$$
\phi e_{k-1}=e_{k-1}, \quad \phi e_{k}=\lambda e_{k-1}+(1-\lambda) e_{k}, \quad \phi e_{n}=e_{n} /(1-\lambda), \quad \phi e_{j}=e_{j} \quad \text { for } j \neq k-1, k, n
$$

and $\psi \in \operatorname{SL}(n)$ by

$$
\psi e_{k-1}=\lambda e_{k-1}+(1-\lambda) e_{k}, \quad \psi e_{k}=e_{k}, \quad \psi e_{n}=e_{n} / \lambda, \quad \psi e_{j}=e_{j} \quad \text { for } j \neq k-1, k, n
$$

By the $\mathrm{SL}(n)$ covariance and since $\mu\left(T^{k-1}\right)=0$, similar to (2.2), we have $\left(\phi+\psi-I_{n}\right) \mu\left(T^{k}\right)=$ 0 . This implies $z_{1}=\cdots=z_{k}=0$. Therefore, the proof of Lemma 3.4 is complete.

Finally, we obtain the following classification.
Proof of Theorem 1.4. It is clear that the moment vector is an $\operatorname{SL}(n)$ covariant valuation on $\mathcal{P}_{0}^{n}$. It remains to show the reverse statement.

We use the dissection in Definition 2. By (2.4), Lemma 3.3 and Lemma 3.4, we obtain for $s>0$

$$
\mu\left(\sqrt[n]{s} T^{n}\right)=\lambda^{-1 / n} \phi_{2} \mu\left(\sqrt[n]{\lambda s} T^{n}\right)+(1-\lambda)^{-1 / n} \psi_{2} \mu\left(\sqrt[n]{(1-\lambda) s} T^{n}\right)
$$

By Proposition 3.1, there exists a function $f:[0, \infty) \rightarrow \mathbb{R}$ such that $\mu\left(T^{n}\right)=f(1) \mathbf{1}$ and

$$
\mathbf{1} f\left(s^{\frac{1}{n}}\right)=\lambda^{-\frac{1}{n}} \phi_{2} \mathbf{1} f\left((s \lambda)^{\frac{1}{n}}\right)+(1-\lambda)^{-\frac{1}{n}} \psi_{2} \mathbf{1} f\left((s(1-\lambda))^{\frac{1}{n}}\right) .
$$

In other words,

$$
\begin{aligned}
& f\left(s^{\frac{1}{n}}\right)=\lambda^{\frac{n-1}{n}} f\left((s \lambda)^{\frac{1}{n}}\right)+(1-\lambda)^{-\frac{1}{n}}(1+\lambda) f\left((s(1-\lambda))^{\frac{1}{n}}\right), \\
& f\left(s^{\frac{1}{n}}\right)=(2-\lambda) \lambda^{-\frac{1}{n}} f\left((s \lambda)^{\frac{1}{n}}\right)+(1-\lambda)^{\frac{n-1}{n}} f\left((s(1-\lambda))^{\frac{1}{n}}\right), \\
& f\left(s^{\frac{1}{n}}\right)=\lambda^{-\frac{1}{n}} f\left((s \lambda)^{\frac{1}{n}}\right)+(1-\lambda)^{-\frac{1}{n}} f\left((s(1-\lambda))^{\frac{1}{n}}\right) .
\end{aligned}
$$

We set $s=a+b, \lambda=a /(a+b)$ for $a, b>0$ and $g(x)=x^{-\frac{1}{n}} f\left(x^{\frac{1}{n}}\right)$ for $x>0$ to get

$$
\begin{aligned}
g(a+b) & =g(a)+g(b), \\
g(a) / g(b) & =a / b .
\end{aligned}
$$

Hence, $f(x)=a x^{n+1}$. By Proposition 3.1 and $m\left(s T^{n}\right)=s^{n+1} \mathbf{1} /(n+1)$ !, we know that $\mu\left(s T^{n}\right)=a s^{n+1} \mathbf{1}=a(n+1)!m\left(s T^{n}\right)$. In other words, there exists a constant $c \in \mathbb{R}$ such that $\mu\left(s T^{n}\right)=c m\left(s T^{n}\right)$. Therefore, $\mu(T)=c m(T)$ for each $T \in \mathcal{T}^{n}$. Next, we dissect $P \in \mathcal{P}_{0}^{n}$ into simplices with one vertex at the origin. Since $\mu$ is simple and by the inclusion-exclusion principle, we obtain $\mu(P)=c m(P)$.

## $4 \operatorname{SL}(n)$ covariant valuations on $\mathcal{P}^{n}$

### 4.1 The two-dimensional case

First, we consider $s \tilde{T}^{1}$ for $s>0$.
Lemma 4.1. If $\mu: \mathcal{P}^{2} \rightarrow \mathbb{R}^{2}$ is an $\mathrm{SL}(2)$ covariant valuation, then there exist constants $c_{1}, c_{2} \in \mathbb{R}$ and a solution of Cauchy's functional equation $\beta:[0, \infty) \rightarrow \mathbb{R}$ such that

$$
\mu\left(s \tilde{T}^{1}\right)=\tilde{c}_{1} m\left(\left[0, s \tilde{T}^{1}\right]\right)+\tilde{c}_{2} s\left(e_{1}+e_{2}\right)+\frac{\beta\left(s^{2}\right)}{s}\left(e_{1}-e_{2}\right)
$$

for $s>0$.
Proof. First, we decompose $\mu$ as $\mu=\mu^{+}+\mu^{-}$, where $\mu^{+}$is an $\mathrm{SL}^{ \pm}(2)$ covariant valuation and $\mu^{-}$is an $\mathrm{SL}^{ \pm}(2)$ signum covariant one.

Next, let $v=\left(v_{1}, v_{2}\right)^{t} \in \mathbb{R}^{2}$ with $v_{1} v_{2} \neq 0$. We have $v=\rho_{1} e_{1}=\rho_{2} e_{1}$ for the same $\rho_{1}$ and $\rho_{2}$ as in the proof of Lemma 3.1. The $\mathrm{SL}^{ \pm}(2)$ covariance of $\mu^{+}$implies

$$
\begin{aligned}
\mu^{+}(\{v\}) & =\mu^{+}\left(\rho_{1}\left\{e_{1}\right\}\right)=\rho_{1} \mu^{+}\left\{e_{1}\right\} \\
& =\mu^{+}\left(\rho_{2}\left\{e_{1}\right\}\right)=\rho_{2} \mu^{+}\left\{e_{1}\right\} .
\end{aligned}
$$

Setting $\mu^{+}\left(\left\{e_{1}\right\}\right)=\left(\tilde{x}_{1}^{+}, \tilde{x}_{2}^{+}\right)^{t}$, we obtain

$$
\begin{aligned}
v_{1} \tilde{x}_{1}^{+} & =v_{1} \tilde{x}_{1}^{+} \\
v_{2} \tilde{x}_{1}^{+}+\tilde{x}_{2}^{+} / v_{1} & =v_{2} \tilde{x}_{1}^{+}-\tilde{x}_{2}^{+} / v_{1} .
\end{aligned}
$$

Thus $\tilde{x}_{2}^{+}=0$ and there exists a constant $\tilde{c} \in \mathbb{R}$ such that $\mu^{+}\left(\left\{e_{1}\right\}\right)=\tilde{c} e_{1}$. For $s>0$, applying the same $\rho_{0}$ as in the proof of Lemma 3.1, we obtain

$$
\begin{equation*}
\mu^{+}\left(\left\{s e_{1}\right\}\right)=\mu^{+}\left(\rho_{0}\left\{e_{1}\right\}\right)=\rho_{0} \mu^{+}\left(\left\{e_{1}\right\}\right)=\tilde{c} s e_{1} . \tag{4.1}
\end{equation*}
$$

On the other hand, the $\mathrm{SL}^{ \pm}(2)$ signum covariance of $\mu^{-}$implies

$$
\begin{aligned}
\mu^{-}(\{v\}) & =\mu^{-}\left(\rho_{1}\left\{e_{1}\right\}\right)=\rho_{1} \mu^{-}\left(\left\{e_{1}\right\}\right) \\
& =\mu^{-}\left(\rho_{2}\left\{e_{1}\right\}\right)=-\rho_{2} \mu^{-}\left(\left\{e_{1}\right\}\right) \\
& =\mu^{-}\left(\rho_{3}\left\{e_{1}\right\}\right)=\rho_{3} \mu^{-}\left(\left\{e_{1}\right\}\right),
\end{aligned}
$$

where $\rho_{3}$ is the same as in the proof of Lemma 3.1. Setting $\mu^{-}\left(\left\{e_{1}\right\}\right)=\left(\tilde{x}_{1}^{-}, \tilde{x}_{2}^{-}\right)^{t}$, we obtain

$$
\begin{aligned}
v_{1} \tilde{x}_{1}^{-} & =-v_{1} \tilde{x}_{1}^{-}=v_{1} \tilde{x}_{1}^{-}-\tilde{x}_{2}^{-} / v_{2} \\
v_{2} \tilde{x}_{1}^{-}+\tilde{x}_{2}^{-} / v_{1} & =-v_{2} \tilde{x}_{1}^{-}+\tilde{x}_{2}^{-} / v_{1}=v_{2} \tilde{x}_{1}^{-}
\end{aligned}
$$

Thus, $\tilde{x}_{1}^{-}=\tilde{x}_{2}^{-}=0$, which implies $\mu^{-}\left(\left\{e_{1}\right\}\right)=0$. Similarly, we have

$$
\begin{equation*}
\mu^{-}\left(\left\{s e_{1}\right\}\right)=0 \tag{4.2}
\end{equation*}
$$

for $s>0$ and $\mu(\{v\})=\mu\left(\rho_{1}\left\{e_{1}\right\}\right)=\rho_{1}\left(\mu^{+}\left\{e_{1}\right\}+\mu^{-}\left\{e_{1}\right\}\right)=\tilde{c} v$.
Second, we use the dissection in Definition 2. By the valuation property of $\mu^{+},(2.4)$ and (4.1), we obtain

$$
\mu^{+}\left(\sqrt{s} \tilde{T}^{1}\right)+\tilde{c} \sqrt{s}(\lambda, 1-\lambda)^{t}=\sqrt{\lambda}^{-1} \phi_{2} \mu^{+}\left(\sqrt{\lambda s} \tilde{T}^{1}\right)+\sqrt{1-\lambda}^{-1} \psi_{2} \mu^{+}\left(\sqrt{(1-\lambda) s} \tilde{T}^{1}\right)
$$

Setting $\lambda=a /(a+b)$ and $s=a+b$ for $a, b>0$, we have

$$
\frac{1}{\sqrt{a+b}} \mu^{+}\left(\sqrt{a+b} \tilde{T}^{1}\right)+\frac{c}{a+b}(a, b)^{t}=\frac{1}{\sqrt{a}} \phi_{2} \mu^{+}\left(\sqrt{a} \tilde{T}^{1}\right)+\frac{1}{\sqrt{b}} \psi_{2} \mu^{+}\left(\sqrt{b} \tilde{T}^{1}\right)
$$

Write $g^{+}(x)=\mu^{+}\left(\sqrt{x} \tilde{T}^{1}\right) / \sqrt{x}=\left(g_{1}^{+}(x), g_{2}^{+}(x)\right)^{t}$ for $x>0$. Then, the equation above becomes

$$
\begin{align*}
& g_{1}^{+}(a+b)+\frac{\tilde{c} a}{a+b}=\frac{a}{a+b} g_{1}^{+}(a)+g_{1}^{+}(b)+\frac{a}{a+b} g_{2}^{+}(b),  \tag{4.3}\\
& g_{2}^{+}(a+b)+\frac{\tilde{c} b}{a+b}=\frac{b}{a+b} g_{1}^{+}(a)+g_{2}^{+}(a)+\frac{b}{a+b} g_{2}^{+}(b) .
\end{align*}
$$

Similar to the proof of Lemma 3.1, we obtain $g_{1}^{+}=g_{2}^{+}$. Combined with (4.3), it follows that there exist constants $\tilde{c}_{1}^{\prime}, \tilde{c}_{2}$ such that $g_{1}^{+}(x)=g_{2}^{+}(x)=\tilde{c}_{1}^{\prime} x+\tilde{c}_{2}$, where $\tilde{c}_{2}=\tilde{c} / 2$. Therefore,

$$
\begin{equation*}
\mu^{+}\left(s \tilde{T}^{1}\right)=\tilde{c}_{1}^{\prime} s^{3}\left(e_{1}+e_{2}\right)+\tilde{c}_{2} s\left(e_{1}+e_{2}\right)=\tilde{c}_{1} m\left(\left[0, s \tilde{T}^{1}\right]\right)+\tilde{c}_{2} s\left(e_{1}+e_{2}\right) \tag{4.4}
\end{equation*}
$$

where $\tilde{c}_{1}=6 \tilde{c}_{1}^{\prime}$ and in the second step we use $m\left(\left[0, s \tilde{T}^{1}\right]\right)=s^{3}\left(e_{1}+e_{2}\right) / 3$ !.

On the other hand, by the valuation property of $\mu^{-}$, (2.4) and (4.2), we obtain

$$
\mu^{-}\left(\sqrt{s} \tilde{T}^{1}\right)=\sqrt{\lambda}^{-1} \phi_{2} \mu^{-}\left(\sqrt{\lambda s} \tilde{T}^{1}\right)+\sqrt{1-\lambda}^{-1} \psi_{2} \mu^{-}\left(\sqrt{(1-\lambda) s} \tilde{T}^{1}\right)
$$

Putting $\lambda=a /(a+b)$ and $s=a+b$ for $a, b>0$, we obtain

$$
\frac{1}{\sqrt{a+b}} \mu^{-}\left(\sqrt{a+b} \tilde{T}^{1}\right)=\frac{1}{\sqrt{a}} \phi_{2} \mu^{-}\left(\sqrt{a} \tilde{T}^{1}\right)+\frac{1}{\sqrt{b}} \psi_{2} \mu^{-}\left(\sqrt{b} \tilde{T}^{1}\right)
$$

Write $g^{-}(x)=\mu^{-}\left(\sqrt{x} \tilde{T}^{1}\right) / \sqrt{x}=\left(g_{1}^{-}(x), g_{2}^{-}(x)\right)^{t}$ for $x>0$. Then, the equation above becomes

$$
\begin{aligned}
& g_{1}^{-}(a+b)=\frac{a}{a+b} g_{1}^{-}(a)+g_{1}^{-}(b)+\frac{a}{a+b} g_{2}^{-}(b), \\
& g_{2}^{-}(a+b)=\frac{b}{a+b} g_{1}^{-}(a)+g_{2}^{-}(a)+\frac{b}{a+b} g_{2}^{-}(b) .
\end{aligned}
$$

Moreover, applying the same $\sigma$ as in the proof of Lemma 3.1, we have $\mu^{-}\left(s \tilde{T}^{1}\right)=\mu^{-}\left(\sigma s \tilde{T}^{1}\right)=$ $-\sigma \mu^{-}\left(s \tilde{T}^{1}\right)$. Then $\mu_{1}^{-}\left(s \tilde{T}^{1}\right)+\mu_{2}^{-}\left(s \tilde{T}^{1}\right)=0$, which implies $g_{1}^{-}+g_{2}^{-}=0$. Hence

$$
(a+b) g_{1}^{-}(a+b)=a g_{1}^{-}(a)+b g_{1}^{-}(b)
$$

Therefore, $g_{1}^{-}(x)=-g_{2}^{-}(x)=\beta(x) / x$, where $\beta:[0, \infty) \rightarrow \mathbb{R}$ is a solution of Cauchy's functional equation. It follows that

$$
\begin{equation*}
\mu^{-}\left(s \tilde{T}^{1}\right)=\frac{\beta\left(s^{2}\right)}{s}\left(e_{1}-e_{2}\right) \tag{4.5}
\end{equation*}
$$

Combining (4.4) and (4.5) completes the proof.
Next, we derive the representation for one-dimensional convex polygons.
Lemma 4.2. If $\mu: \mathcal{P}^{2} \rightarrow \mathbb{R}^{2}$ is an $\mathrm{SL}(2)$ covariant valuation, then there exist constants $c_{2}, \tilde{c}_{1}, \tilde{c}_{2}$ and a solution of Cauchy's functional equation $\beta:[0, \infty) \rightarrow \mathbb{R}$ such that

$$
\mu(P)= \begin{cases}\tilde{c}_{1} m([0, P])+\tilde{c}_{2}\left(v_{1}+v_{2}\right)+\frac{\beta\left(\operatorname{det}\left(v_{1}, v_{2}\right)\right)}{\operatorname{det}\left(v_{1}, v_{2}\right)}\left(v_{1}-v_{2}\right), & \text { if } 0 \notin \operatorname{aff} P \text { and } \operatorname{det}\left(v_{1}, v_{2}\right)>0 ; \\ 2\left(\tilde{c}_{2}-c_{2}\right) v_{1}+2 c_{2} v_{2}, & \text { if } 0 \in \operatorname{aff} P \backslash P,\end{cases}
$$

for every line segment $P=\left[v_{1}, v_{2}\right]$ in $\mathcal{P}^{2}$.

Proof. First, assume that $0 \notin$ aff $P$ and $\phi=\left(v_{1}, v_{2}\right) \in G L(2)$ such that $\phi e_{1}=v_{1}$ and $\phi e_{2}=v_{2}$. By Lemma 4.1, there exist constants $\tilde{c}_{1}, \tilde{c}_{2} \in \mathbb{R}$ and a solution of Cauchy's functional equation $\beta:[0, \infty) \rightarrow \mathbb{R}$ such that

$$
\begin{aligned}
\mu(P)=\mu\left(\phi \tilde{T}^{1}\right) & ={\sqrt{\operatorname{det}\left(v_{1}, v_{2}\right)}}^{-1} \phi \mu\left(\sqrt{\operatorname{det}\left(v_{1}, v_{2}\right)} \tilde{T}^{1}\right) \\
& =\tilde{c}_{1} m([0, P])+\tilde{c}_{2}\left(v_{1}+v_{2}\right)+\frac{\beta\left(\operatorname{det}\left(v_{1}, v_{2}\right)\right)}{\operatorname{det}\left(v_{1}, v_{2}\right)}\left(v_{1}-v_{2}\right) .
\end{aligned}
$$

Second, assume that $0 \in \operatorname{aff} P \backslash P$. Then, $0, v_{1}$ and $v_{2}$ are on the same line. Since $\mu$ is a valuation, we obtain $\mu\left(\left[0, v_{1}\right]\right)+\mu\left(\left[v_{1}, v_{2}\right]\right)=\mu\left(\left[0, v_{2}\right]\right)+\mu\left(\left\{v_{1}\right\}\right)$. Since there exists a constant $c_{2} \in \mathbb{R}$ such that $\mu([0, v])=2 c_{2} v$ and $\mu\left(\left\{v_{1}\right\}\right)=2 \tilde{c}_{2} v_{1}$, we have $\mu(P)=2\left(\tilde{c}_{2}-c_{2}\right) v_{1}+2 c_{2} v_{2}$.

Finally, we treat convex polygons of dimension two.
Lemma 4.3. If $\mu: \mathcal{P}^{2} \rightarrow \mathbb{R}^{2}$ is an $\mathrm{SL}(2)$ covariant valuation, then there exist constants $c_{1}, c_{2}, \tilde{c}_{1}, \tilde{c}_{2} \in \mathbb{R}$ and solutions of Cauchy's functional equation $\alpha, \gamma:[0, \infty) \rightarrow \mathbb{R}$ such that
$\mu(P)=\left(c_{1}-\tilde{c}_{1}\right) m(P)+\tilde{c}_{1} m([0, P])+c_{2} e([0, P])+\tilde{c}_{2} e\left(\left[0, v_{1}, \ldots, v_{r}\right]\right)+h_{\alpha}([0, P])+\sum_{i=2}^{r} h_{\gamma}\left(\left[0, v_{i-1}, v_{i}\right]\right)$
for every $P \in \mathcal{P}^{2} \backslash \mathcal{P}_{0}^{2}$ with $\operatorname{dim} P=2$, vertices $v_{1}, \ldots, v_{r}$ visible from the origin and labeled counter-clockwisely.

Proof. Let $P \in \mathcal{P}^{2} \backslash \mathcal{P}_{0}^{2}$. Let $E_{i}=\left[v_{i}, v_{i+1}\right]$ be the edges of $P$ visible from the origin for $i=1, \ldots, r$. Assume that the edges $E_{1}, E_{2}, \cdots, E_{r}$ are labeled counter-clockwisely. Clearly, $[0, P]=P \cup\left[0, E_{1}\right] \cup \cdots \cup\left[0, E_{r}\right]$. Note that $[0, P],\left[0, E_{1}\right], \ldots,\left[0, E_{r}\right] \in \mathcal{P}_{0}^{2}$. By the inclusionexclusion principle, Theorem 1.5 and (4.1), we have

$$
\begin{aligned}
\mu([0, P])= & \mu(P)+\sum_{i=1}^{r} \mu\left[0, E_{i}\right]-\sum_{i=1}^{r} \mu(\underbrace{\left[0, E_{i}\right] \cap P}_{=E_{i}})-\sum_{1 \leq j<k \leq r} \mu(\underbrace{\left[0, E_{j}\right] \cap\left[0, E_{k}\right]}_{\in \mathcal{P}_{0}^{2}}) \\
& +\sum_{1 \leq j<k \leq r} \mu\left(\left[0, E_{j}\right] \cap\left[0, E_{k}\right] \cap P\right) .
\end{aligned}
$$

Thus, there exist solutions of Cauchy's functional equation $\alpha, \beta, \gamma:[0, \infty) \rightarrow \mathbb{R}$, such that

$$
\begin{aligned}
\mu(P)= & \mu([0, P])-\sum_{i=1}^{r} \mu\left[0, E_{i}\right]+\sum_{i=1}^{r} \mu\left(E_{i}\right)+\sum_{i=2}^{r-1} \mu\left(\left[0, v_{i}\right]\right)-\sum_{i=2}^{r-1} \mu\left(\left\{v_{i}\right\}\right) \\
= & c_{1} m([0, P])+c_{2} e([0, P])+h_{\alpha}([0, P])-c_{1} m(\operatorname{cl}([0, P] \backslash P))-c_{2}\left(v_{1}+2 \sum_{i=1}^{r-1} v_{i}+v_{r}\right) \\
& -\sum_{i=2}^{r} \frac{\alpha\left(\operatorname{det}\left(v_{i-1}, v_{i}\right)\right)}{\operatorname{det}\left(v_{i-1}, v_{i}\right)}\left(v_{i-1}-v_{i}\right)+\tilde{c}_{1} m(\operatorname{cl}([0, P] \backslash P))+\tilde{c}_{2}\left(v_{1}+\sum_{i=2}^{r-1} v_{i}+v_{r}\right) \\
& +\sum_{i=2}^{r} \frac{\beta\left(\operatorname{det}\left(v_{i-1}, v_{i}\right)\right)}{\operatorname{det}\left(v_{i-1}, v_{i}\right)}\left(v_{i-1}-v_{i}\right)+2 c_{2} \sum_{i=2}^{r-1} v_{i}-2 \tilde{c}_{2} \sum_{i=2}^{r-1} v_{i} \\
= & \left(c_{1}-\tilde{c}_{1}\right) m(P)+\tilde{c}_{1} m([0, P])+h_{\alpha}([0, P])+c_{2} e([0, P])+\tilde{c}_{2}\left(v_{1}+v_{r}\right) \\
& -\sum_{i=2}^{r} \frac{\alpha\left(\operatorname{det}\left(v_{i-1}, v_{i}\right)\right)}{\operatorname{det}\left(v_{i-1}, v_{i}\right)}\left(v_{i-1}-v_{i}\right)+\sum_{i=2}^{r} \frac{\beta\left(\operatorname{det}\left(v_{i-1}, v_{i}\right)\right)}{\operatorname{det}\left(v_{i-1}, v_{i}\right)}\left(v_{i-1}-v_{i}\right) \\
= & \left(c_{1}-\tilde{c}_{1}\right) m(P)+\tilde{c}_{1} m([0, P])+h_{\alpha}([0, P])+c_{2} e([0, P])+\tilde{c}_{2}\left(v_{1}+v_{r}\right) \\
& +\sum_{i=2}^{r} \gamma \frac{\alpha\left(\operatorname{det}\left(v_{i-1}, v_{i}\right)\right)}{\operatorname{det}\left(v_{i-1}, v_{i}\right)}\left(v_{i-1}-v_{i}\right) \\
= & \left(c_{1}-\tilde{c}_{1}\right) m(P)+\tilde{c}_{1} m([0, P])+\tilde{c}_{2} e([0, P])+\tilde{c}_{2} e\left(\left[0, v_{1}, \ldots, v_{r}\right]\right)+h_{\alpha}([0, P]) \\
& +\sum_{i=2}^{r} h_{\gamma}\left(\left[0, v_{i-1}, v_{i}\right]\right) .
\end{aligned}
$$

Using Theorem 1.5, Lemma 4.2 and Lemma 4.3, we complete the proof of Theorem 1.7. Similarly, we obtain Corollary 1.2.

### 4.2 The higher-dimensional case

We consider $\operatorname{SL}(n)$ covariant valuations on $\tilde{\mathcal{T}}^{k}$ for the three-dimensional case and the $n$ dimensional case for $n \geq 4$, respectively.
Lemma 4.4. If $\mu: \mathcal{P}^{3} \rightarrow \mathbb{R}^{3}$ is an $\mathrm{SL}(3)$ covariant valuation, then $\mu(T)=0$ for every $T \in \tilde{\mathcal{T}}^{k}$ with $0 \leq k \leq 1$.
Proof. It suffices to consider the valuation on $\left\{e_{1}\right\}, \tilde{T}^{1}$ and $\tilde{T}^{2}$. First, applying the same $\sigma_{1}$ as in the proof of Proposition 3.2 shows that there exists a constant $c \in \mathbb{R}$ such that $\mu\left(\left\{e_{1}\right\}\right)=\mu\left(\sigma_{1}\left\{e_{1}\right\}\right)=\sigma_{1} \mu\left(\left\{e_{1}\right\}\right)=2 c e_{1}$.

Let $\mu\left(\tilde{T}^{1}\right)=\left(x_{1}, x_{2}, x_{3}\right)^{t}$ and $\sigma_{2}$ be the same as in the proof of Proposition 3.2. The $\mathrm{SL}(3)$ covariance of $\mu$ implies that $\mu\left(\tilde{T}^{1}\right)=\mu\left(\sigma_{2} \tilde{T}^{1}\right)=\sigma_{2} \mu\left(\tilde{T}^{1}\right)$. Then $\mu\left(\tilde{T}^{1}\right)=\left(x_{1}, x_{1}, 0\right)^{t}$. Let $v=\lambda e_{1}+(1-\lambda) e_{2}$ where $\lambda \in(0,1)$. We use the dissection in Definition 1. By the valuation property of $\mu$, we have

$$
\mu\left(\tilde{T}^{1}\right)+\mu(\{v\})=\mu\left(\phi_{1} \tilde{T}^{1}\right)+\mu\left(\psi_{1} \tilde{T}^{1}\right) .
$$

Using the $\operatorname{SL}(3)$ covariance of $\mu$ we obtain $\mu\left(\tilde{T}^{1}\right)=c\left(e_{1}+e_{2}\right)$. Let $\tilde{T}_{23}=\left[e_{2}, e_{3}\right]$. Since $\mu\left(\tilde{T}_{23}\right)=\mu\left(\sigma_{0} \tilde{T}^{1}\right)=\sigma_{0} \mu\left(\tilde{T}^{1}\right)$ for the same $\sigma_{0}$ as in the proof of Proposition 3.1, we have $\mu\left(\tilde{T}_{23}\right)=c\left(e_{2}+e_{3}\right)$. Note that

$$
\begin{equation*}
\mu\left(s \tilde{T}_{23}\right)=\mu\left(\rho \tilde{T}_{23}\right)=\rho \mu\left(\tilde{T}_{23}\right)=c s\left(e_{2}+e_{3}\right) \tag{4.6}
\end{equation*}
$$

for the same $\rho$ as in the proof of Lemma 3.3 and every $s>0$.
Next, we use the dissection in Definition 2. By (2.4), (3.3) and (4.6), it follows that

$$
\mu\left(\sqrt[3]{s} \tilde{T}^{2}\right)+c \sqrt[3]{s}(\lambda, 1-\lambda, 1)^{t}=\lambda^{-1 / 3} \phi_{2} \mu\left(\sqrt[3]{\lambda s} \tilde{T}^{2}\right)+(1-\lambda)^{-1 / 3} \psi_{2} \mu\left(\sqrt[3]{(1-\lambda) s} \tilde{T}^{2}\right)
$$

Setting $\lambda=a /(a+b), s=a+b$ for $a, b>0$ and $g(x)=\mu\left(\sqrt[3]{x} \tilde{T}^{2}\right) / \sqrt[3]{x}=\left(g_{1}(x), g_{2}(x), g_{3}(x)\right)^{t}$ for $x>0$, we obtain

$$
\begin{aligned}
g_{1}(a+b)+\frac{c a}{a+b} & =\frac{a}{a+b} g_{1}(a)+g_{1}(b)+\frac{a}{a+b} g_{2}(b), \\
g_{2}(a+b)+\frac{c b}{a+b} & =\frac{b}{a+b} g_{1}(a)+g_{2}(a)+\frac{b}{a+b} g_{2}(b), \\
g_{3}(a+b)+c & =g_{3}(a)+g_{3}(b) .
\end{aligned}
$$

Due to Proposition 3.1, we have $g_{1}(x)=g_{2}(x)=g_{3}(x)$. It follows that $\mu\left(\left\{e_{1}\right\}\right)=\mu\left(\tilde{T}^{1}\right)=$ 0 .

Lemma 4.5. Let $n \geq 4$. If $\mu: \mathcal{P}^{n} \rightarrow \mathbb{R}^{n}$ is an $\mathrm{SL}(n)$ covariant valuation, then $\mu(T)=0$ for every $T \in \tilde{\mathcal{T}}^{k}$ with $0 \leq k \leq n-2$.

Proof. It suffices to prove that $\mu$ vanishes on $\tilde{\mathcal{T}}^{k}$ for $0 \leq k \leq n-2$. We prove the statement by induction on $k=\operatorname{dim} T$. For $k=0$, write $\mu\left(\left\{e_{1}\right\}\right)=x=\left(x_{1} \ldots, x_{n}\right)^{t}$. By the $\operatorname{SL}(n)$ covariance of $\mu$, we have $\mu\left(\left\{e_{1}\right\}\right)=\mu\left(\sigma_{3}\left\{e_{1}\right\}\right)=\sigma_{3} \mu\left(\left\{e_{1}\right\}\right)$. Hence $x_{2}=\cdots=x_{n}=0$ and there exists a constant $\underset{\sim}{c}$ such that $\mu\left(\left\{e_{1}\right\}\right)=2 c e_{1}$.

For $k=1$, write $\mu\left(\tilde{T}^{1}\right)=\left(x_{1}, \ldots, x_{n}\right)^{t}$. Using the $\operatorname{SL}(n)$ covariance of $\mu$, we have $\mu\left(\tilde{T}^{1}\right)=$ $\mu\left(\sigma_{4} \tilde{T}^{1}\right)=\sigma_{4} \mu\left(\tilde{T}^{1}\right)$ and $\mu\left(\tilde{T}^{1}\right)=\mu\left(\sigma_{5} \tilde{T}^{1}\right)=\sigma_{5} \mu\left(\tilde{T}^{1}\right)$ for the same $\sigma_{4}$ and $\sigma_{5}$ as in the proof of Lemma 3.4. Therefore $x_{1}=x_{2}$ and $x_{3}=x_{4}=\cdots=x_{n}=0$. Moreover, we know that $\mu\left(\tilde{T}^{1}\right)=c\left(e_{1}+e_{2}\right)$ and $\mu\left(\left[e_{2}, e_{3}\right]\right)=c\left(e_{2}+e_{3}\right)$.

For $k=2$, write $\mu\left(\tilde{T^{2}}\right)=\left(y_{1}, \ldots, y_{n}\right)^{t}$. By the $\operatorname{SL}(n)$ covariance of $\mu$, we have $\mu\left(\tilde{T^{2}}\right)=$ $\mu\left(\sigma_{6} T^{2}\right)=\sigma_{6} \mu\left(\tilde{T}^{2}\right)$ and $\mu\left(\tilde{T}^{2}\right)=\mu\left(\sigma_{7} \tilde{T}^{2}\right)=\sigma_{7} \mu\left(\tilde{T^{2}}\right)$ for the same $\sigma_{6}$ and $\sigma_{7}$ as in the proof of Lemma 3.4. This yields $y_{1}=y_{2}=y_{3}$ and $y_{4}=\cdots=y_{n}=0$. We use the dissection Definition 1. Since $\mu$ is an $\operatorname{SL}(n)$ covariant valuation, we have $\left(\phi_{1}+\psi_{1}-I_{n}\right) \mu\left(\tilde{T}^{2}\right)=\psi_{1} \mu\left(\left[e_{2}, e_{3}\right]\right)$. Thus, the equation above is equivalent to $y_{1}=c=0$. Therefore, we obtain $\mu\left(\left\{e_{1}\right\}\right)=\mu\left(\tilde{T}^{1}\right)=$ $\mu\left(\tilde{T}^{2}\right)=0$.

Next assume that $\mu(\tilde{T})=0$ for all $\tilde{T}$ with $\operatorname{dim} \tilde{T} \leq k-1$. We prove the statement for $\operatorname{dim} \tilde{T}=k \leq n-2$. By the induction hypothesis we know that $\mu\left(\tilde{T}^{k-1}\right)=0$. Let $\mu\left(\tilde{T}^{k}\right)=\left(z_{1}, \ldots, z_{n}\right)^{t}$. By the $\operatorname{SL}(n)$ covariance, we have $\mu\left(\tilde{T}^{k}\right)=\mu\left(\sigma_{8} \tilde{T}^{k}\right)=\sigma_{8} \mu\left(\tilde{T}^{k}\right)$ and $\mu\left(\tilde{T}^{k}\right)=\mu\left(\sigma_{9} \tilde{T}^{k}\right)=\sigma_{9} \mu\left(\tilde{T}^{k}\right)$ for the same $\sigma_{8}$ and $\sigma_{9}$ as in the proof of Lemma 3.4. Therefore, $z_{1}=\cdots=z_{k}$, and $z_{k+1}=\cdots=z_{n}=0$.

Denote by $H_{\lambda}$ the hyperplane through $\lambda e_{k-1}+(1-\lambda) e_{k}$ and $e_{i}$ for $i \neq k-1, k$. Then $H_{\lambda}$ dissects $\tilde{T}^{k}$ into $\phi_{2} \tilde{T}^{k}$ and $\psi_{2} \tilde{T}^{k}$ in a way that is similar to the dissection in Definition 1. Since $\mu$ is a valuation, we have

$$
\mu\left(\tilde{T}^{k}\right)+\mu\left(\psi_{2} \tilde{T}^{k-1}\right)=\mu\left(\phi_{2} \tilde{T}^{k}\right)+\mu\left(\psi_{2} \tilde{T}^{k}\right)
$$

By the $\mathrm{SL}(n)$ covariance and since $\mu\left(\tilde{T}^{k-1}\right)=0$, the equation above can be rewritten as $\left(\phi_{2}+\psi_{2}-I_{n}\right) \mu\left(\tilde{T}^{k}\right)=0$. This yields $z_{1}=\cdots=z_{k}=0$, which completes the proof.

Lemma 4.6. Let $n \geq 3$. If $\mu: \mathcal{P}^{n} \rightarrow \mathbb{R}^{n}$ is an $\operatorname{SL}(n)$ covariant valuation, then $\mu$ vanishes on every polytope $P \in \mathcal{P}^{n}$ with $\operatorname{dim} P \leq n-2$.

Proof. Note that $\mu$ vanishes on at most $(n-1)$-dimensional polytopes in $\mathcal{P}_{0}^{n}$ and thus we just need to take care of polytopes in $\mathcal{P}^{n} \backslash \mathcal{P}_{0}^{n}$. We assume that $P \in \mathcal{P}^{n} \backslash \mathcal{P}_{0}^{n}$ and prove the statement by induction on $k=\operatorname{dim} P$. For $k=0$, by Lemma 4.4 and Lemma 4.5 , we have $\mu(\{x\})=\mu\left(\left\{e_{1}\right\}\right)=0$. Assume $\mu(P)=0$ for all $P \in \mathcal{P}^{n} \backslash \mathcal{P}_{0}^{n}$ with $\operatorname{dim} P \leq k-1$. We prove the statement for $\operatorname{dim} P=k \leq n-2$.

First, let $P$ be a $k$-dimensional polytope with $0 \notin$ aff $P$. Triangulate $P$ into $k$-dimensional simplices $T_{1}, \ldots, T_{r}$. By the inclusion-exclusion principle, the induction assumption, Lemma 4.4 and Lemma 4.5, we have $\mu(P)=0$.

Second, let $P$ be a $k$-dimensional polytope with $0 \in \operatorname{aff} P$. Let $F_{1}, \ldots, F_{r}$ be the facets of $P$ visible from the origin. Triangulate the facets $F_{i}$ into $(k-1)$-dimensional simplices $T_{1}^{\prime}, \ldots, T_{l}^{\prime}$ and thus the closure of $[0, P] \backslash P$ into simplices $T_{1}=\left[0, T_{1}^{\prime}\right], \ldots, T_{l}=\left[0, T_{l}^{\prime}\right]$ with a vertex at the origin. Using the inclusion-exclusion principle, that $\mu$ vanishes on $\mathcal{P}_{0}^{n}$ and the
induction assumption, we have

$$
\begin{aligned}
0=\mu(\underbrace{[0, P]}_{\in \mathcal{P}_{0}^{n}})= & \sum_{j=1}^{r}(-1)^{j-1} \sum_{1 \leq i_{1} \leq \cdots \leq i_{j} \leq r} \mu(\underbrace{T_{i_{1}} \cap \cdots \cap T_{i_{j}}}_{\in \mathcal{P}_{0}^{n}}) \\
& +\sum_{j=1}^{r}(-1)^{j} \sum_{1 \leq i_{1} \leq \cdots \leq i_{j} \leq r} \mu(\underbrace{T_{i_{1}} \cap \cdots \cap T_{i_{j}} \cap P}_{\operatorname{dim} \leq k-1})+\mu(P) \\
= & \mu(P) .
\end{aligned}
$$

This completes the proof.
Next, we establish the classification on all convex polytopes of dimension $n-1$.
Lemma 4.7. Let $n \geq 3$. If $\mu: \mathcal{P}^{n} \rightarrow \mathbb{R}^{n}$ is an $\mathrm{SL}(n)$ covariant valuation, then there exists a constant $\tilde{c} \in \mathbb{R}$ such that

$$
\mu(P)=\tilde{c} m([0, P])
$$

for every $(n-1)$-dimensional polytope $P \in \mathcal{P}^{n}$.
Proof. First, it suffices to consider $s \tilde{T}^{n-1}$ for $s>0$. We use the dissection in Definition 2. By (2.4), (3.3) and Lemma 4.6, we have

$$
\mu\left(\sqrt[n]{s} \tilde{T}^{n-1}\right)=\lambda^{-1 / n} \phi_{2} \mu\left(\sqrt[n]{\lambda s} \tilde{T}^{n-1}\right)+(1-\lambda)^{-1 / n} \psi_{2} \mu\left(\sqrt[n]{(1-\lambda) s} \tilde{T}^{n-1}\right)
$$

Similar to Proposition 3.1, there exists a function $f$ on $\mathbb{R}$ such that $\mu\left(\tilde{T}^{n-1}\right)=f(1) \mathbf{1}$ and

$$
\mathbf{1} f\left(s^{\frac{1}{n}}\right)=\lambda^{-\frac{1}{n}} \phi_{2} \mathbf{1} f\left((s \lambda)^{\frac{1}{n}}\right)+(1-\lambda)^{-\frac{1}{n}} \psi_{2} \mathbf{1} f\left((s(1-\lambda))^{\frac{1}{n}}\right) .
$$

Furthermore, using a similar argument as in the proof of Theorem 1.4, we obtain that there exists a constant $c_{2} \in \mathbb{R}$ such that

$$
\begin{equation*}
\mu\left(s \tilde{T}^{n-1}\right)=c_{2} m\left(\left[0, s \tilde{T}^{n-1}\right]\right) \tag{4.7}
\end{equation*}
$$

Second, let $P$ be an $(n-1)$-dimensional polytope with $0 \notin$ aff $P$. Triangulate $P$ into simplices $T_{1}, \ldots, T_{r}$. Using the inclusion-exclusion principle, (4.7) and Lemma 4.6, we have

$$
\mu(P)=\sum_{j=1}^{r} \mu\left(T_{j}\right)=c_{2} m([0, P]) .
$$

Finally, let $P$ be an $(n-1)$-dimensional polytope with $0 \in$ aff $P$. Then the polytope $[0, P]$ is $(n-1)$-dimensional and $m([0, P])=0$. Thus, for $P \in \mathcal{P}_{0}^{n}$ the assertion is trivial. Assume
that $0 \notin P$ and triangulate the facets of $P$ visible from the origin as in the proof of Lemma 4.6. Dissect the closure of $[0, P] \backslash P$ into simplices $T_{1}, \ldots, T_{r}$ with a vertex at the origin. From Lemma 3.3, Lemma 3.4, Lemma 4.6 and the inclusion-exclusion principle, we obtain

$$
0=\mu([0, P])=\sum_{j=1}^{r} \mu\left(T_{j}\right)+\mu(P)=\mu(P)
$$

which completes the proof of the lemma.
Finally, we establish the classification in Theorem 1.6.
Proof of Theorem 1.6. It is clear that the expression in (1.1) is an SL( $n$ ) covariant valuation. It remains to show the reverse statement.

For $P \in \mathcal{P}_{0}^{n}$, by $m(\operatorname{cl}([0, P] \backslash P))=0$ and Theorem 1.4, the assertion holds. So we focus on the polytopes in $\mathcal{P}^{n} \backslash \mathcal{P}_{0}^{n}$. Assume that $P \in \mathcal{P}^{n} \backslash \mathcal{P}_{0}^{n}$ with dimension $n$. Let $F_{1}, \ldots, F_{r}$ be the facets of $P$ visible from the origin. By Theorem 1.4, Lemma 4.6, Lemma 4.7 and the inclusion-exclusion principle, there exist constants $c, \tilde{c} \in \mathbb{R}$ such that

$$
\begin{aligned}
\operatorname{cm}([0, P])= & \mu([0, P]) \\
= & \sum_{j=1}^{r}(-1)^{j-1} \sum_{1 \leq i_{1} \leq \cdots \leq i_{j} \leq r} \mu(\underbrace{\left[0, F_{i_{1}}\right] \cap \cdots \cap\left[0, F_{i_{j}}\right]}_{\in \mathcal{P}_{0}^{n}}) \\
& +\sum_{j=2}^{r}(-1)^{j} \sum_{1 \leq i_{1} \leq \cdots \leq i_{j} \leq r} \mu(\underbrace{\left[0, F_{i_{1}}\right] \cap \cdots \cap\left[0, F_{i_{j}}\right] \cap P}_{\operatorname{dim} \leq n-2}) \\
& -\sum_{i=1}^{r} \mu(\underbrace{\left[0, F_{i}\right] \cap P}_{=F_{i}})+\sum_{i=1}^{r} \mu\left(\left[0, F_{i}\right]\right)+\mu(P) \\
= & \sum_{i=1}^{r} \mu\left[0, F_{i}\right]+\mu(P)-\sum_{i=1}^{r} \mu\left(F_{i}\right) \\
= & c \sum_{i=1}^{r} m\left(\left[0, F_{i}\right]\right)+\mu(P)-\tilde{c} \sum_{i=1}^{r} m\left(\left[0, F_{i}\right]\right) .
\end{aligned}
$$

Since the moment vector is a simple valuation on $\mathcal{P}^{n}$, we have $\mu(P)=(c-\tilde{c}) m(P)+$ $\tilde{c} m([0, P])$.

## Acknowledgement

The authors wish to thank the referee for valuable suggestions and careful reading of the original manuscript. The work of the first author was supported in part by Chinese Scholarship Council and by Natural Science Foundation Project of CSTC (Grant No. cstc2017jcyjAX0022). The work of the second author was supported in part by Shanghai Sailing Program 17YF1413800 and by the National Natural Science Foundation of China (Project 11701373). The second author is the corresponding author.

## References

[1] S. Alesker. Continuous rotation invariant valuations on convex sets. Ann. Math. (2), 149(3):977-1005, 1999.
[2] S. Alesker. Description of translation invariant valuations on convex sets with solution of P. McMullen's conjecture. Geom. Funct. Anal., 11(2):244-272, 2001.
[3] C. Haberl. Blaschke valuations. Amer. J. Math., 133(3):717-751, 2011.
[4] C. Haberl. Minkowski valuations intertwining the special linear group. J. Eur. Math. Soc., 14(5):1565-1597, 2012.
[5] C. Haberl and L. Parapatits. The centro-affine Hadwiger theorem. J. Amer. Math. Soc., 27(3):685-705, 2014.
[6] C. Haberl and L. Parapatits. Valuations and surface area measures. J. Reine Angew. Math., 687:225-245, 2014.
[7] C. Haberl and L. Parapatits. Moments and valuations. Amer. J. Math., 138(6):15751603, 2016.
[8] C. Haberl and L. Parapatits. Centro-affine tensor valuations. Adv. Math., 316:806-865, 2017.
[9] D. A. Klain. Star valuations and dual mixed volumes. Adv. Math., 121(1):80-101, 1996.
[10] D. A. Klain and G. C. Rota. Introduction to Geometric Probability. Cambridge University Press, Cambridge, 1997.
[11] J. Li and G. Leng. $L_{p}$ Minkowski valuations on polytopes. Adv. Math., 299:139-173, 2016.
[12] J. Li and D. Ma. Laplace transforms and valuations. J. Funct. Anal., 272(2):738-758, 2017.
[13] J. Li, S. Yuan, and G. Leng. L $p_{p}$-Blaschke valuations. Trans. Amer. Math. Soc., 367(5):3161-3187, 2015.
[14] M. Ludwig. Moment vectors of polytopes. Rend. Circ. Mat. Pale. (2) Suppl., 70:123-138, 2002.
[15] M. Ludwig. Projection bodies and valuations. Adv. Math., 172(2):158-168, 2002.
[16] M. Ludwig. Valuations on polytopes containing the origin in their interiors. Adv. Math., 170:239-256, 2002.
[17] M. Ludwig. Ellipsoids and matrix-valued valuations. Duke Math. J., 119(1):159-188, 2003.
[18] M. Ludwig. Minkowski valuations. Trans. Amer. Math. Soc., 357(10):4191-4213, 2005.
[19] M. Ludwig. Intersection bodies and valuations. Amer. J. Math., 128(6):1409-1428, 2006.
[20] M. Ludwig. Minkowski areas and valuations. J. Differential Geom., 86(1):133-161, 2010.
[21] M. Ludwig. Fisher information and matrix-valued valuations. Adv. Math., 226(3):27002711, 2011.
[22] M. Ludwig and M. Reitzner. A classification of $\mathrm{SL}(n)$ invariant valuations. Ann. Math. (2), 172(2):1219-1267, 2010.
[23] M. Ludwig and M. Reitzner. $\mathrm{SL}(n)$ invariant valuations on polytopes. Discrete Comput. Geom., 57(3):571-581, 2017.
[24] L. Parapatits. SL( $n$ )-contravariant $L_{p}$-Minkowski valuations. Trans. Amer. Math. Soc., 366(3):1195-1211, 2014.
[25] L. Parapatits. SL(n)-covariant $L_{p}$-Minkowski valuations. J. London Math. Soc. (2), 89(2):397-414, 2014.
[26] R. Schneider. Convex Bodies: the Brunn-Minkowski Theory. Cambridge University Press, Cambridge, 2nd expanded edition, 2014.
[27] F. E. Schuster and T. Wannerer. GL $(n)$ contravariant Minkowski valuations. Trans. Amer. Math. Soc., 364(2):815-826, 2012.
[28] T. Wannerer. GL(n) equivariant Minkowski valuations. Indiana Univ. Math. J., 60(5):1655-1672, 2011.

