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Stability and slicing inequalities for intersection bodies

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Abstract We prove a generalization of the hyperplane inequality for intersection bodies, where volume is replaced by an arbitrary measure μ with even continuous density and sections are of arbitrary dimension n-k, $1 \le k < n$. If K is a generalized k-intersection body, then

$$\mu(K) \leq \frac{n}{n-k} c_{n,k} \max_{H} \mu(K \cap H) \operatorname{Vol}_n(K)^{k/n}.$$

Here $c_{n,k} = |B_2^n|^{(n-k)/n}/|B_2^{n-k}| < 1$, $|B_2^n|$ is the volume of the unit Euclidean ball, and maximum is taken over all (n-k)-dimensional subspaces of \mathbb{R}^n . The constant is optimal, and for each intersection body the inequality holds for every k. We also prove a stronger "difference" inequality. The proof is based on stability in the lower dimensional Busemann–Petty problem for arbitrary measures in the following sense. Let $\varepsilon > 0$, $1 \le k < n$. Suppose that K and L are origin-symmetric star bodies in \mathbb{R}^n , and K is a generalized k-intersection body. If for every (n-k)-dimensional subspace H of \mathbb{R}^n

$$\mu(K \cap H) < \mu(L \cap H) + \varepsilon$$
,

then

$$\mu(K) \le \mu(L) + \frac{n}{n-k} c_{n,k} \operatorname{Vol}_n(K)^{k/n} \varepsilon.$$

Keywords Convex bodies · Volume · Sections

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1 Introduction

The Busemann–Petty problem, posed in 1956 in [7], asks the following question. Suppose that K and L are origin-symmetric convex bodies in \mathbb{R}^n so that

$$\operatorname{Vol}_{n-1}(K \cap \xi^{\perp}) \le \operatorname{Vol}_{n-1}(L \cap \xi^{\perp}), \quad \forall \xi \in S^{n-1},$$

where ξ^{\perp} is the central hyperplane perpendicular to ξ . Does it follow that

$$\operatorname{Vol}_n(K) \leq \operatorname{Vol}_n(L)$$
?

The answer is affirmative if $n \le 4$ and negative if $n \ge 5$. The solution was completed at the end of the 90's as the result of a sequence of papers [1,5,10,11,13,14,18,19,26,27,31,36–38]; see [20, p. 3] or [12, p. 343] for details.

It is natural to ask what happens if hyperplane sections are replaced by sections of lower dimensions. Suppose that for every (n-k)-dimensional subspace $H \in \mathbb{R}^n$,

$$\operatorname{Vol}_{n-k}(K \cap H) < \operatorname{Vol}_{n-k}(L \cap H).$$

Does it follow that

$$\operatorname{Vol}_n(K) \leq \operatorname{Vol}_n(L)$$
?

Zhang [39] proved that the answer is affirmative if and only if all origin-symmetric convex bodies in \mathbb{R}^n are generalized k-intersection bodies (see definition in Sect. 2; this is similar to the connection between the original Busemann–Petty problem and intersection bodies established by Lutwak in [27]). Using this connection, Bourgain and Zhang [6] proved that the answer is negative if the dimension of sections n - k > 3 (see also [33] and different later proof in [21]). However, the cases of two- and three-dimensional sections remain open. Other results on the lower dimensional Busemann–Petty problem can be found in [28–30,32–35].

In this paper, we establish stability in the affirmative part of the lower dimensional Busemann–Petty problem. Stability problems in convex geometry have been considered for a long time; see [16] for numerous results and references. Stability in volume comparison problems was first studied in [22], where such results were proved for the Busemann–Petty and Shephard problems. We extend the result of [22, Theorem 1] to sections of lower dimensions in the following way.

Theorem 1 Let K and L be origin-symmetric star bodies in \mathbb{R}^n , and $1 \le k < n$. Suppose K is a generalized k-intersection body and $\varepsilon > 0$. If for every (n - k)-dimensional subspace H of \mathbb{R}^n

$$Vol_{n-k}(K \cap H) < Vol_{n-k}(L \cap H) + \varepsilon, \tag{1}$$

then

$$\operatorname{Vol}_{n}(K)^{\frac{n-k}{n}} \le \operatorname{Vol}_{n}(L)^{\frac{n-k}{n}} + c_{n,k} \, \varepsilon, \tag{2}$$

where $c_{n,k} = |B_2^n|^{(n-k)/n}/|B_2^{n-k}|$ and $|B_2^n|$ is the volume of the unit Euclidean ball.

Note that $c_{n,k} < 1$, which immediately follows from the log-convexity of the Γ -function (see for example [24, Lemma 2.1]). Also, in the formulation of Theorem 1 in [22] the constant $c_{n,1}$ was replaced by 1, though the proof there gives the result with $c_{n,1}$.

Zvavitch [40] found a remarkable generalization of the Busemann–Petty problem to arbitrary measures. It appears that one can replace volume by any measure with even continuous



density in \mathbb{R}^n . Let f be an even continuous non-negative function on \mathbb{R}^n , and denote by μ the measure on \mathbb{R}^n with density f. For every closed bounded set $B \subset \mathbb{R}^n$ define

$$\mu(B) = \int_{B} f(x) \, dx.$$

It was proved in [40] that, for $n \le 4$ and any origin-symmetric convex bodies K and L in \mathbb{R}^n , the inequalities

$$\mu(K \cap \xi^{\perp}) \le \mu(L \cap \xi^{\perp}), \quad \forall \xi \in S^{n-1}$$

imply

$$\mu(K) \leq \mu(L)$$
.

Zvavitch also proved that this is generally not true if $n \ge 5$, namely, for any μ with strictly positive even continuous density there exist K and L providing a counterexample.

Stability in Zvavitch's result was established in [23, Theorem 2]. Here we extend this result to sections of lower dimensions, as follows.

Theorem 2 Let K and L be origin-symmetric star bodies in \mathbb{R}^n , and 1 < k < n. Suppose K is a generalized k-intersection body and $\varepsilon > 0$. If for every (n - k)-dimensional subspace H of \mathbb{R}^n

$$\mu(K \cap H) \le \mu(L \cap H) + \varepsilon,$$
 (3)

then

$$\mu(K) \le \mu(L) + \frac{n}{n-k} c_{n,k} \operatorname{Vol}_n(K)^{k/n} \varepsilon.$$

In the case $f \equiv 1$, we get another stability result for volume which is weaker than what is provided by Theorem 1. This is the reason why we state Theorem 1 separately. However, for arbitrary measures the constant in Theorem 2 is the best possible, as follows from the example after Corollary 5.

The stability results mentioned above were applied in [22,23] to the hyperplane (or slicing) problem of Bourgain [2,3] that can be formulated as follows. Does there exist an absolute constant C so that for any origin-symmetric convex body K in \mathbb{R}^n

$$\operatorname{Vol}_{n}(K)^{\frac{n-1}{n}} \leq C \max_{\xi \in S^{n-1}} \operatorname{Vol}_{n-1}(K \cap \xi^{\perp})? \tag{4}$$

The best-to-date estimate $C \sim n^{1/4}$ is due to Klartag [17], who removed the logarithmic term from the previous estimate of Bourgain [4]. We refer the reader to recent papers [8,9] for the history and current state of the hyperplane problem.

In the case where K is an intersection body (see Sect. 2 for definitions and properties), the inequality (4) is known for sections of arbitrary dimension with the best possible constant. For any $1 \le k < n$,

$$\operatorname{Vol}_{n}(K)^{\frac{n-k}{n}} \le c_{n,k} \max_{H \in G(n,n-k)} \operatorname{Vol}_{n-k}(K \cap H), \tag{5}$$

where G(n, n - k) is the Grassmanian of (n - k)-dimensional subspaces of \mathbb{R}^n , and the equality is attained when $K = B_2^n$. In particular, if the dimension $n \le 4$, then (5) is true for any origin-symmetric convex body K. The proof is an immediate consequence of Zhang's



connection between generalized intersection bodies and the lower dimensional Busemann–Petty problem; apply this connection to any generalized k-intersection body K and $L = B_2^n$. Then use the fact that every intersection body is a generalized k-intersection body for every k (see [15] or [28]). For every fixed k, the inequality (5) holds for any generalized k-intersection body K.

We prove several generalizations of (5) using the stability results formulated above. First, interchanging K and L in Theorem 1, we get the following "difference" inequality, previously established in [22, Corollary 1] in the hyperplane case.

Corollary 3 Let K and L be origin-symmetric star bodies in \mathbb{R}^n , and $1 \le k < n$. Suppose K and L are generalized k-intersection bodies, then

$$\left| \operatorname{Vol}_{n}(K)^{\frac{n-k}{n}} - \operatorname{Vol}_{n}(L)^{\frac{n-k}{n}} \right|$$

$$\leq c_{n,k} \max_{H \in G(n,n-k)} \left| \operatorname{Vol}_{n-k}(K \cap H) - \operatorname{Vol}_{n-k}(L \cap H) \right|.$$

Putting $L = \emptyset$ in the latter inequality, we get (5) for any generalized k-intersection body K.

Interchanging K and L in Theorem 2, we get the following inequality, which was earlier proved for k = 1 in [23, Corollary 1].

Corollary 4 Let K and L be origin-symmetric star bodies in \mathbb{R}^n , and $1 \le k < n$. Suppose that K and L are generalized k-intersection bodies. Then

$$|\mu(K) - \mu(L)| \le \frac{n}{n-k} c_{n,k} \max_{H} |\mu(K \cap H) - \mu(L \cap H)| \max \left\{ \operatorname{Vol}_n(K)^{k/n}, \operatorname{Vol}_n(L)^{k/n} \right\},$$

where maximum is taken over all (n-k)-dimensional subspaces H of \mathbb{R}^n .

Putting $L = \emptyset$, we generalize to lower dimensions the hyperplane inequality for arbitrary measures from [23, Theorem 1].

Corollary 5 Let $1 \le k < n$, and suppose that K is a generalized k-intersection body in \mathbb{R}^n . Then

$$\mu(K) \le \frac{n}{n-k} c_{n,k} \max_{H \in G(n,n-k)} \mu(K \cap H) \operatorname{Vol}_n(K)^{k/n}. \tag{6}$$

The constant in the right-hand side is the best possible. In fact, let $K = B_2^n$ and, for every $j \in N$, let f_j be a non-negative continuous function on [0,1] supported in $(1-\frac{1}{j},1)$ and such that $\int_0^1 f_j(t)dt = 1$. Let μ_j be the measure on \mathbb{R}^n with density $f_j(|x|_2)$, where $|x|_2$ is the Euclidean norm. We have

$$\mu_j(B_2^n) = |S^{n-1}| \int_0^1 r^{n-1} f_j(r) dr,$$

where $|S^{n-1}| = 2\pi^{n/2}/\Gamma(n/2)$ is the surface area of the unit sphere in \mathbb{R}^n . For every $H \in G(n, n-k)$,

$$\mu_j(B_2^n \cap H) = |S^{n-k-1}| \int_0^1 r^{n-k-1} f_j(r) dr.$$



Clearly,

$$\lim_{j \to \infty} \frac{\int_0^1 r^{n-1} f_j(r) dr}{\int_0^1 r^{n-k-1} f_j(r) dr} = 1.$$

Using $|S^{n-1}| = n|B_2^n|$, we get

$$\lim_{j\to\infty} \frac{\mu_j(B_2^n)}{\max_H \mu_j(B_2^n \cap H) \operatorname{Vol}_n(B_2^n)^{k/n}} = \frac{|S^{n-1}|}{|S^{n-k-1}||B_2^n|^{k/n}} = \frac{n}{n-k} c_{n,k},$$

which shows that the constant is asymptotically optimal.

2 Stability

We say that a closed bounded set K in \mathbb{R}^n is a *star body* if every straight line passing through the origin crosses the boundary of K at exactly two points different from the origin, the origin is an interior point of K, and the *Minkowski functional* of K defined by

$$||x||_K = \min\{a \ge 0 : x \in aK\}$$

is a continuous function on \mathbb{R}^n .

The radial function of a star body K is defined by

$$\rho_K(x) = ||x||_K^{-1}, \quad x \in \mathbb{R}^n.$$

If $x \in S^{n-1}$ then $\rho_K(x)$ is the radius of K in the direction of x.

Writing the volume of K in polar coordinates, one gets

$$Vol_{n}(K) = \frac{1}{n} \int_{S^{n-1}} \rho_{K}^{n}(\theta) d\theta = \frac{1}{n} \int_{S^{n-1}} \|\theta\|_{K}^{-n} d\theta.$$
 (7)

The spherical Radon transform $R: C(S^{n-1}) \mapsto C(S^{n-1})$ is a linear operator defined by

$$Rf(\xi) = \int_{S^{n-1} \cap \xi^{\perp}} f(x) \, dx, \quad \xi \in S^{n-1}$$

for every function $f \in C(S^{n-1})$.

The polar formula (7) for the volume of a hyperplane section expresses this volume in terms of the spherical Radon transform (see for example [20, p.15]):

$$S_K(\xi) = \text{Vol}_{n-1}(K \cap \xi^{\perp}) = \frac{1}{n-1} R(\|\cdot\|_K^{-n+1})(\xi).$$
 (8)

The spherical Radon transform is self-dual (see [16, Lemma 1.3.3]): for any functions $f, g \in C(S^{n-1})$

$$\int_{S^{n-1}} Rf(\xi) g(\xi) d\xi = \int_{S^{n-1}} f(\xi) Rg(\xi) d\xi.$$
 (9)

Using self-duality, one can extend the spherical Radon transform to measures. Let μ be a finite Borel measure on S^{n-1} . We define the spherical Radon transform of μ as a functional $R\mu$ on the space $C(S^{n-1})$ acting by



$$(R\mu, f) = (\mu, Rf) = \int_{S^{n-1}} Rf(x)d\mu(x).$$

By Riesz's characterization of continuous linear functionals on the space $C(S^{n-1})$, $R\mu$ is also a finite Borel measure on S^{n-1} . If μ has continuous density g, then by (9) the Radon transform of μ has density Rg.

The class of intersection bodies was introduced by Lutwak [27]. Let K, L be origin-symmetric star bodies in \mathbb{R}^n . We say that K is the intersection body of L if the radius of K in every direction is equal to the (n-1)-dimensional volume of the section of L by the central hyperplane orthogonal to this direction, i.e. for every $\xi \in S^{n-1}$,

$$\rho_K(\xi) = \|\xi\|_K^{-1} = \text{Vol}_{n-1}(L \cap \xi^{\perp}). \tag{10}$$

All the bodies *K* that appear as intersection bodies of different star bodies form *the class of intersection bodies of star bodies*.

Note that the right-hand side of (10) can be written in terms of the spherical Radon transform using (8):

$$\|\xi\|_K^{-1} = \frac{1}{n-1} \int\limits_{S^{n-1} \cap \xi^{\perp}} \|\theta\|_L^{-n+1} d\theta = \frac{1}{n-1} R(\|\cdot\|_L^{-n+1})(\xi).$$

It means that a star body K is the intersection body of a star body if and only if the function $\|\cdot\|_K^{-1}$ is the spherical Radon transform of a continuous positive function on S^{n-1} . This allows to introduce a more general class of bodies. A star body K in \mathbb{R}^n is called an *intersection body* if there exists a finite Borel measure μ on the sphere S^{n-1} so that $\|\cdot\|_K^{-1} = R\mu$ as functionals on $C(S^{n-1})$, i.e. for every continuous function f on S^{n-1} ,

$$\int_{S^{n-1}} \|x\|_K^{-1} f(x) \, dx = \int_{S^{n-1}} Rf(x) \, d\mu(x). \tag{11}$$

Intersection bodies played the crucial role in the solution of the original Busemann–Petty problem due to the following connection found by Lutwak [27]. If K in an origin-symmetric intersection body in \mathbb{R}^n and L is any origin-symmetric star body in \mathbb{R}^n , then the inequalities $S_K(\xi) \leq S_L(\xi)$ for all $\xi \in S^{n-1}$ imply that $\operatorname{Vol}_n(K) \leq \operatorname{Vol}_n(L)$, i.e. the answer to the Busemann–Petty problem in this situation is affirmative. For more information about intersection bodies, see [20,25, Chapter 4], [12, Chapter 8] and references there. In particular, every origin-symmetric convex body in \mathbb{R}^n , $n \leq 4$ is an intersection body; see [11,38,13]. Also the unit ball of any finite dimensional subspace of L_p , 0 is an intersection body; see [18].

Zhang in [39] introduced a generalization of intersection bodies. For $1 \le k \le n-1$, the (n-k)-dimensional spherical Radon transform is an operator $\mathcal{R}_{n-k}: C(S^{n-1}) \mapsto C(G(n,n-k))$ defined by

$$\mathcal{R}_{n-k}(f)(H) = \int_{\mathbb{S}^{n-1} \cap H} f(x)dx, \quad H \in G(n, n-k).$$

Denote the image of the operator \mathcal{R}_{n-k} by X:

$$\mathcal{R}_{n-k}\left(C(S^{n-1})\right) = X \subset C(G(n, n-k)).$$

Let $M^+(X)$ be the space of linear positive continuous functionals on X, i.e. for every $\nu \in M^+(X)$ and non-negative function $f \in X$, we have $\nu(f) \ge 0$.



An origin-symmetric star body K in \mathbb{R}^n is called a *generalized k-intersection body* if there exists a functional $\nu \in M^+(X)$, so that for every $f \in C(S^{n-1})$,

$$\int_{S^{n-1}} \|x\|_K^{-k} f(x) dx = \nu(\mathcal{R}_{n-k}(f)).$$

When k = 1 we get the class of intersection bodies. It was proved by Grinberg and Zhang [15, Lemma 6.1] that every intersection body in \mathbb{R}^n is a generalized k-intersection body for every k < n. More generally, as proved later by Milman [28], if m divides k, then every generalized m-intersection body is a generalized k-intersection body. Zhang [39] showed that the answer to the lower dimensional Busemann–Petty problem is affirmative if and only if every origin-symmetric convex body in \mathbb{R}^n is a generalized k-intersection body.

Denote by $1_S \equiv 1$ and $1_G \equiv 1$ the functions which are equal to 1 everywhere on the unit sphere S^{n-1} and the Grassmanian G(n, n-k), correspondingly. Then, $\mathcal{R}_{n-k}(1_S) = |S^{n-k-1}| 1_G$.

We are now ready to prove the stability in the lower dimensional Busemann-Petty problem.

Proof of Theorem 1 By the polar formula for volume (7), for each $H \in G(n, n-k)$ we have

$$\operatorname{Vol}_{n-k}(K \cap H) = \frac{1}{n-k} \mathcal{R}_{n-k} \left(\| \cdot \|_{K}^{-n+k} \right) (H), \tag{12}$$

Then the inequality (1) can be written as

$$\mathcal{R}_{n-k}\left(\left\|\cdot\right\|_{K}^{-n+k}\right)(H) \le \mathcal{R}_{n-k}\left(\left\|\cdot\right\|_{L}^{-n+k}\right)(H) + (n-k)\varepsilon. \tag{13}$$

Since K is a generalized k-intersection body, there exists $\mu_0 \in M^+$, such that for each $\psi \in C(S^{n-1})$,

$$\int_{\mathbb{S}^{n-1}} \|x\|_K^{-k} \psi(x) dx = \mu_0(\mathcal{R}_{n-k}(\psi)). \tag{14}$$

Since μ_0 is a positive functional, by (13) and (14), we have

$$n \operatorname{Vol}_{n}(K) = \int_{S^{n-1}} \|x\|_{K}^{-k} \|x\|_{K}^{-n+k} dx$$

$$= \mu_{0} \left(\mathcal{R}_{n-k} \left(\|\cdot\|_{K}^{-n+k} \right) \right)$$

$$\leq \mu_{0} \left(\mathcal{R}_{n-k} \left(\|\cdot\|_{L}^{-n+k} \right) \right) + (n-k)\varepsilon\mu_{0}(1_{G})$$

$$:= I + II. \tag{15}$$

Using (14), Hölder's inequality and polar formula for the volume, we get

$$I = \int_{S^{n-1}} \|x\|_{K}^{-k} \|x\|_{L}^{-n+k} dx$$

$$\leq \left(\int_{S^{n-1}} \|x\|_{K}^{-n} dx\right)^{k/n} \left(\int_{S^{n-1}} \|x\|_{L}^{-n} dx\right)^{(n-k)/n}$$

$$= n \operatorname{Vol}_{n}(K)^{k/n} \operatorname{Vol}_{n}(L)^{(n-k)/n}. \tag{16}$$

Now, by (14), the well-known formula $|S^{n-1}| = n|B_2^n|$ (see [20, p. 33]) and Hölder's inequality,

$$\Pi = (n-k)\varepsilon\mu_{0}(1_{G}) = \frac{(n-k)\varepsilon}{|S^{n-k-1}|} \int_{S^{n-1}} ||x||_{K}^{-k} 1_{S}(x) dx$$

$$\leq \frac{(n-k)\varepsilon}{|S^{n-k-1}|} \left(\int_{S^{n-1}} ||x||_{K}^{-n} dx \right)^{k/n} ||S^{n-1}||^{\frac{n-k}{n}}$$

$$= \frac{n^{k/n} (n-k) |S^{n-1}|^{\frac{n-k}{n}}}{|S^{n-k-1}|} \operatorname{Vol}_{n}(K)^{k/n} \varepsilon$$

$$= \frac{n |B_{2}^{n}|^{\frac{n-k}{n}}}{|B_{2}^{n-k-1}|} \operatorname{Vol}_{n}(K)^{k/n} \varepsilon.$$

Combining this with (15) and (16), we get the result.

We now pass to stability for arbitrary measures. Let μ be a measure on \mathbb{R}^n with even continuous density f. Let χ be the indicator function of the interval [0, 1]. The measure μ of a star body K can be expressed in polar coordinates as follows:

$$\mu(K) = \int_{K} f(x) dx = \int_{\mathbb{R}^{n}} \chi(\|x\|_{K}) f(x) dx$$

$$= \int_{S^{n-1}} \left(\int_{0}^{\|\theta\|_{K}^{-1}} r^{n-1} f(r\theta) dr \right) d\theta.$$
(17)

Similarly, we can express the volume of a section of K by an (n-k)-dimensional subspace H of \mathbb{R}^n as

$$\mu(K \cap H) = \int_{H} \chi (\|x\|_{K}) f(x) dx$$

$$= \int_{S^{n-1} \cap H} \left(\int_{0}^{\|\theta\|_{K}^{-1}} t^{n-k-1} f(t\theta) dt \right) d\theta$$

$$= \mathcal{R}_{n-k} \left(\int_{0}^{\|\theta\|_{K}^{-1}} r^{n-k-1} f(r\theta) dr \right) (H), \tag{18}$$

where the Radon transform is applied to a function of the variable $\theta \in S^{n-1}$.

We need the following lemma, which was also used by Zvavitch in his proof.

Lemma 6 Let $a, b, k \in \mathbb{R}^+$, and α be a non-negative function on $(0, \max\{a, b\})$, such that the integral below converges. Then



$$\int_{0}^{a} r^{n-1} \alpha(r) dt - a^{k} \int_{0}^{a} r^{n-k-1} \alpha(r) dr$$

$$\leq \int_{0}^{b} r^{n-1} \alpha(r) dr - a^{k} \int_{0}^{b} r^{n-k-1} \alpha(r) dr$$

Proof The result follows from

$$a^k \int_a^b r^{n-k-1} \alpha(r) \ dr \le \int_a^b r^{n-1} \alpha(r) \ dr.$$

Proof of Theorem 2 Using (18), inequality (3) can be written as

$$\mathcal{R}_{n-k} \left(\int_{0}^{\|\theta\|_{K}^{-1}} r^{n-k-1} f(r\theta) dr \right) (H)$$

$$\leq \mathcal{R}_{n-k} \left(\int_{0}^{\|\theta\|_{L}^{-1}} r^{n-k-1} f(r\theta) dr \right) (H) + \varepsilon, \quad \forall H \in G(n, n-k). \tag{19}$$

As in the proof of Theorem 1, let μ_0 be the positive functional associated with the generalized k-intersection body K. Applying μ_0 to both sides of (19) and then using (14), we get

$$\int_{S^{n-1}} \|\theta\|_{K}^{-k} \left(\int_{0}^{\|\theta\|_{K}^{-1}} r^{n-k-1} f(r\theta) dr \right) d\theta$$

$$\leq \int_{S^{n-1}} \|\theta\|_{K}^{-k} \left(\int_{0}^{\|\theta\|_{L}^{-1}} r^{n-k-1} f(r\theta) dr \right) d\theta + \varepsilon \mu_{0}(1_{G}). \tag{20}$$

Applying Lemma 6 with $a = \|\theta\|_K^{-1}$, $b = \|\theta\|_L^{-1}$ and $\alpha(r) = f(r\theta)$ and then integrating over the sphere, we get

$$\begin{split} & \int\limits_{0}^{\|\theta\|_{K}^{-1}} r^{n-1} f(r\theta) \ dr - \|\theta\|_{K}^{-k} \int\limits_{0}^{\|\theta\|_{K}^{-1}} r^{n-k-1} f(r\theta) \ dr \\ & \leq \int\limits_{0}^{\|\theta\|_{L}^{-1}} r^{n-1} f(r\theta) \ dr - \|\theta\|_{K}^{-k} \int\limits_{0}^{\|\theta\|_{L}^{-1}} r^{n-k-1} f(r\theta) \ dr, \end{split}$$



and

$$\int_{S^{n-1}} \left(\int_{0}^{\|\theta\|_{K}^{-1}} r^{n-1} f(r\theta) dr \right) d\theta$$

$$- \int_{S^{n-1}} \|\theta\|_{K}^{-k} \left(\int_{0}^{\|\theta\|_{K}^{-1}} r^{n-k-1} f(r\theta) dr \right) d\theta$$

$$\leq \int_{S^{n-1}} \left(\int_{0}^{\|\theta\|_{L}^{-1}} r^{n-1} f(r\theta) dr \right) d\theta$$

$$- \int_{S^{n-1}} \|\theta\|_{K}^{-k} \left(\int_{0}^{\|\theta\|_{L}^{-1}} r^{n-k-1} f(r\theta) dr \right) d\theta. \tag{21}$$

Adding (20) and (21) and using (17) we get

$$\mu(K) \le \mu(L) + \varepsilon \mu_0(1_G).$$

As shown in the proof of Theorem 1,

$$\mu_0(1_G) \le \frac{n}{n-k} c_{n,k} \operatorname{Vol}_n(K)^{k/n},$$

which completes the proof.

As mentioned earlier, every intersection body is a generalized k-intersection body for every k, so if K is an intersection body, the results of Theorems 1 and 2 hold for all k at the same time, as well as the results of Corollaries 3, 4, 5.

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